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# Radiation Scene Reconstruction with Multiple Gamma-Ray Imagers

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U.S. DEPARTMENT  
of ENERGY

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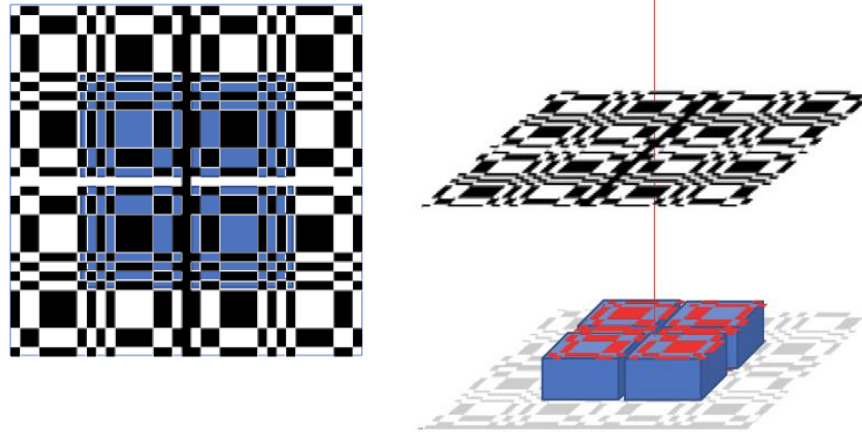
# Gamma-Ray Imaging

- Too high energy for focusing optics!
- Common imaging modes:

**Coded Aperture:**  
 Good Angular Resolution ( $\sim 5^\circ$ )  
 Limited FOV

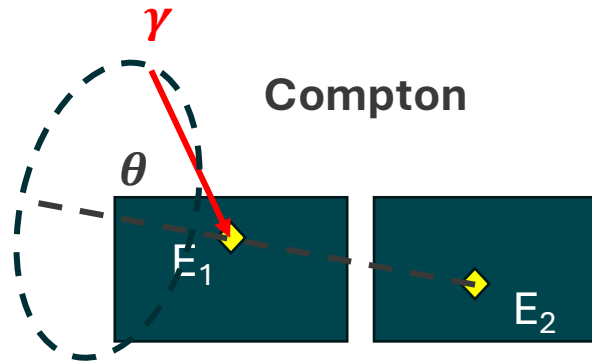
**Compton:**  
 Full-sky coverage  
 Poorer resolution ( $\sim 15^\circ$ )

Coded Aperture

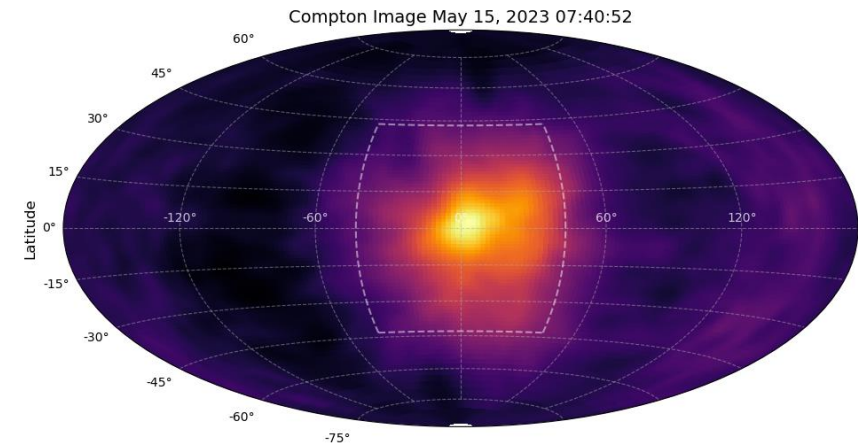
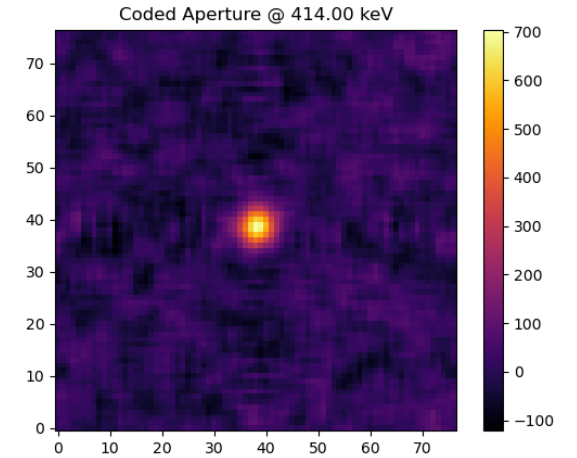


$< 500 \text{ keV}$

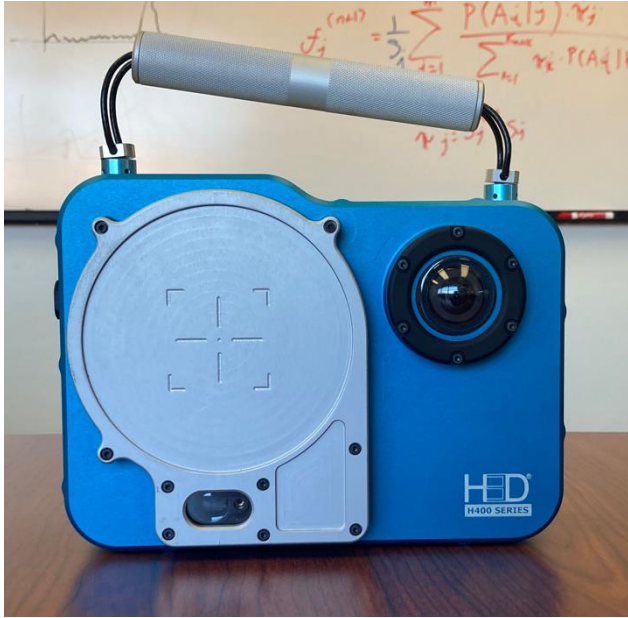
Compton



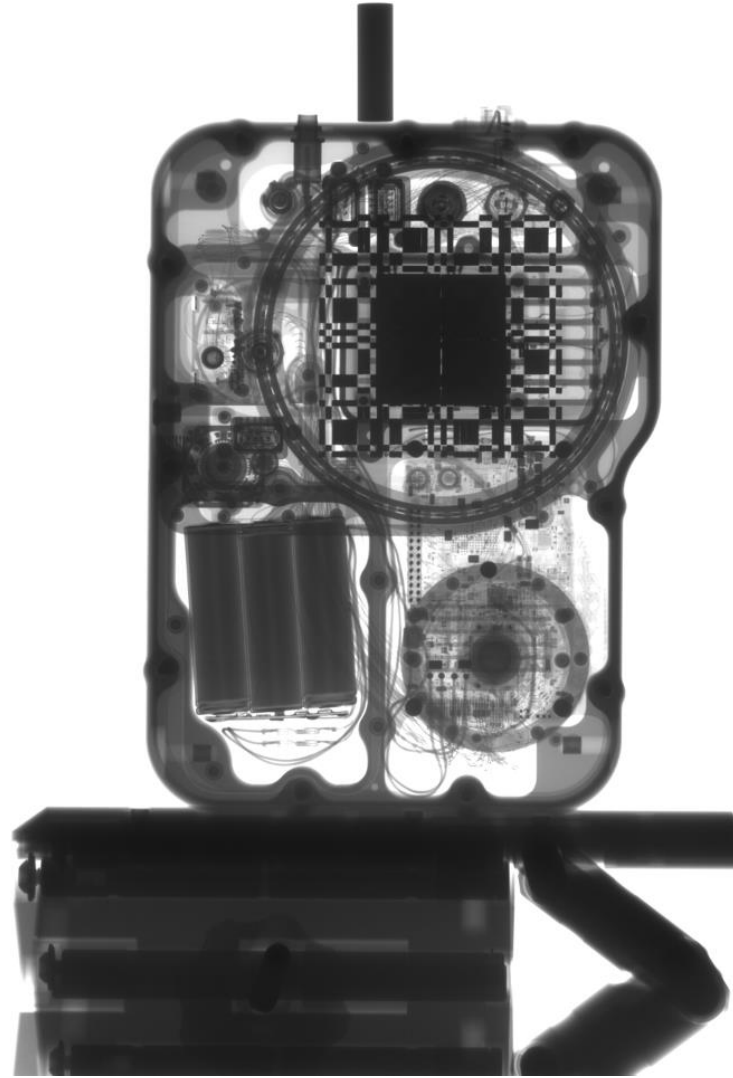
Source in the center of the FOV



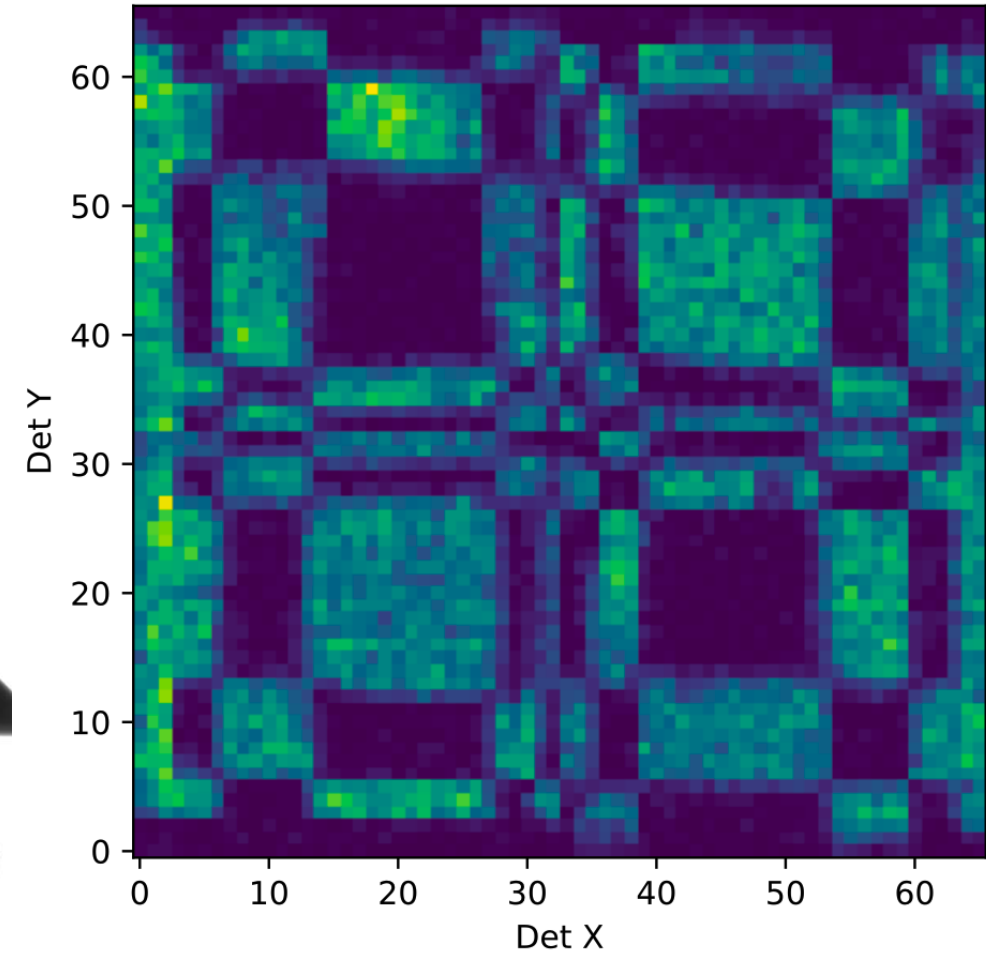
# H3D CZT Imager



- H420 imager capable of coded-ap and Compton imaging.
- Detection element: 4 CZT crystals (2.2 x 2.2 x 1 cm).
- Position-sensitive ( $\sim 0.5$  mm spatial resolution)



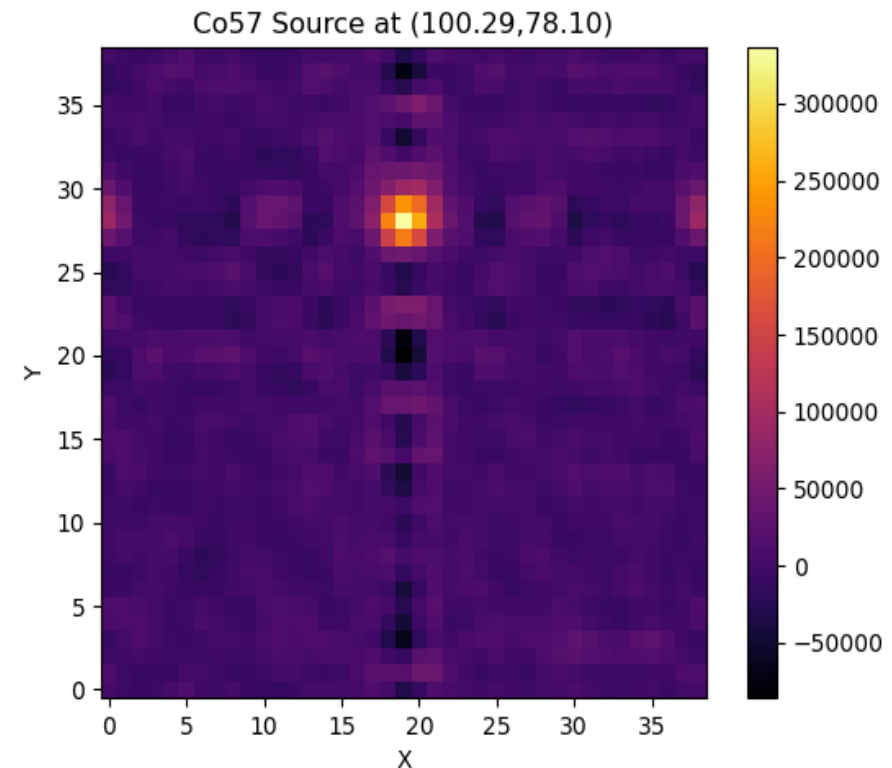
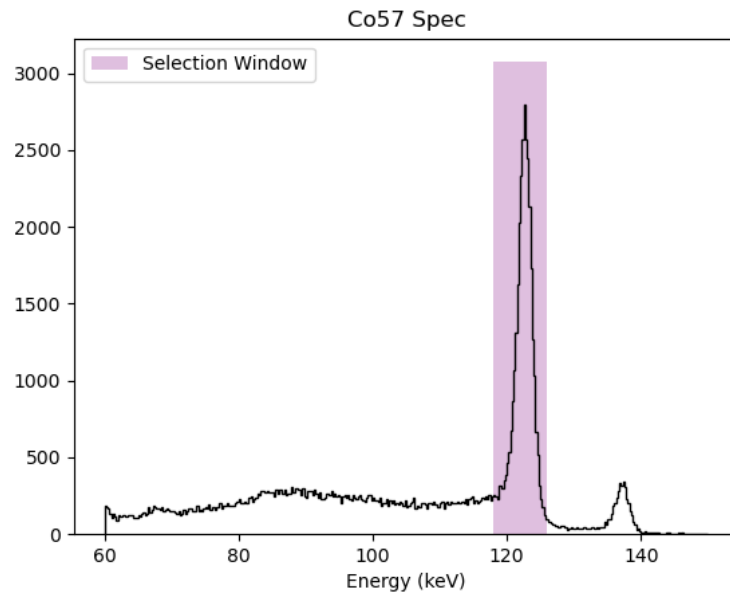
Hallie Mask Pattern



*Mask Hit Pattern for Source Directly in Front of Imager*

# Imaging a Point Source

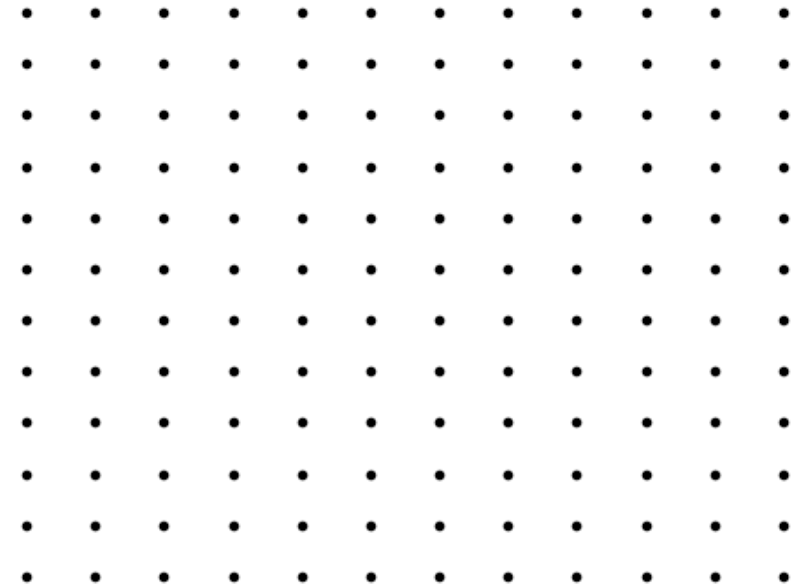
- Co57 calibration source is scanned across the field of view of the detector at a distance of 1 meter.
- These calibrations are necessary for understanding the imaging efficiency as a function of location within the FOV.
- Image created using event selection about the 122 keV peak.



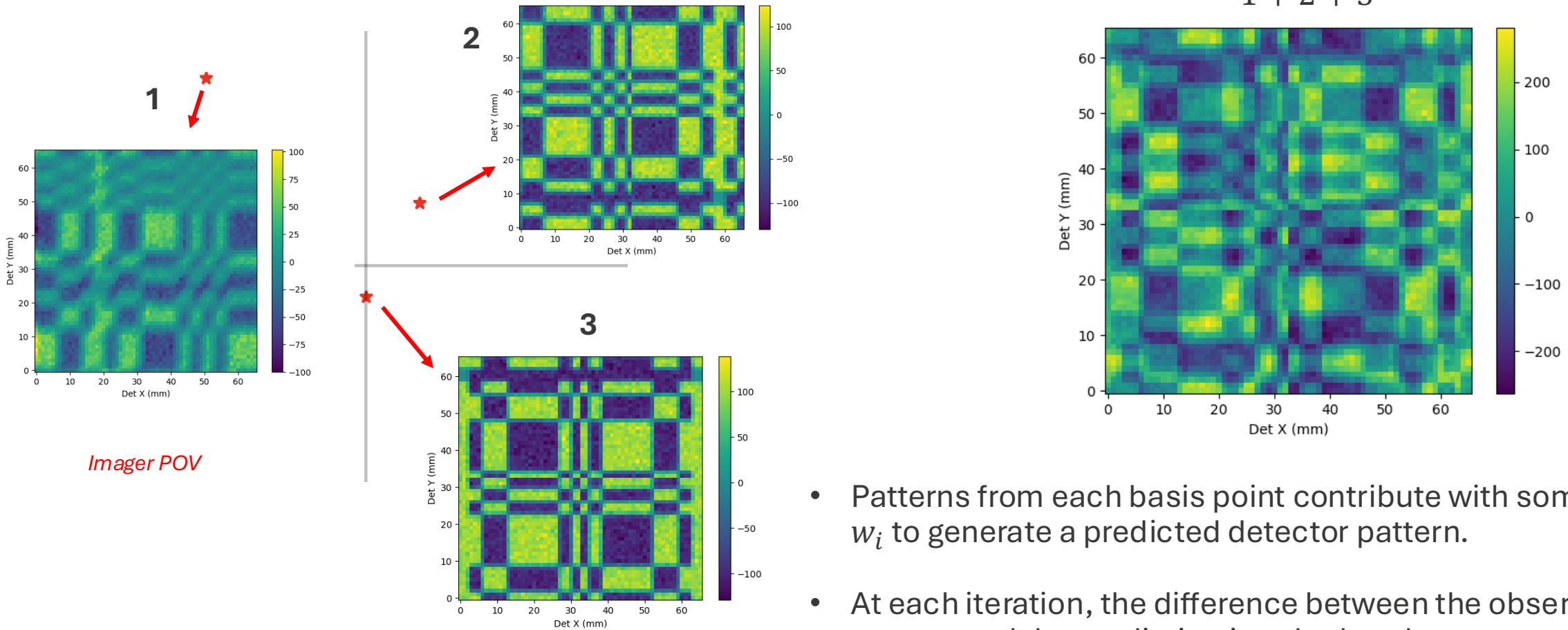
# Linear Regression Reconstruction

Linear regression reconstruction seeks to reproduce the observed data using a combination of precalculated detector responses. It assumes the following:

1. We can predict what the shadow pattern on the detector will look like for any arbitrary location in the field of view (via ray tracing or MC).
2. A basis set of possible patterns can be constructed that represents some volume in the FOV.
3. Any measured detector pattern can be described by some linear combination of the predicted patterns in the constructed basis set.

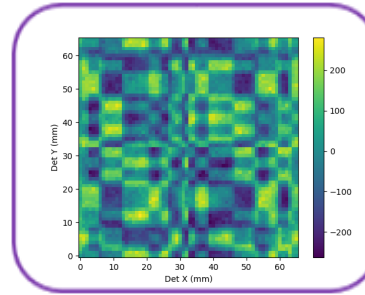
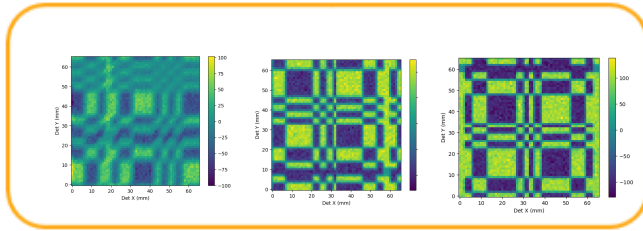


# Linear Regression Reconstruction



- Patterns from each basis point contribute with some weight  $w_i$  to generate a predicted detector pattern.
- At each iteration, the difference between the observed pattern and the prediction is calculated.
- Coefficients for the basis points ( $w_i$ ) are updated until the overall difference between prediction and observation is minimized.

# Elastic Net Model



L1 Norm (Sparsity)

$\alpha$  - penalty strength

$\rho$  - L1 to L2 Ratio

$$\min_w \frac{1}{2n_{\text{samples}}} \underbrace{\|Xw - y\|_2^2}_{\text{Ordinary Least Squares}} + \underbrace{\alpha\rho\|w\|_1}_{\text{L1 Norm (Sparsity)}} + \underbrace{\frac{\alpha(1-\rho)}{2}\|w\|_2^2}_{\text{L2 Norm (Collinearity)}}$$

Hou Zou and Trevor Hastie (2005)

Ordinary Least Squares

L2 Norm (Collinearity)

Elastic net uses two regularization terms to overcome issues that can commonly arise with OLS regression.

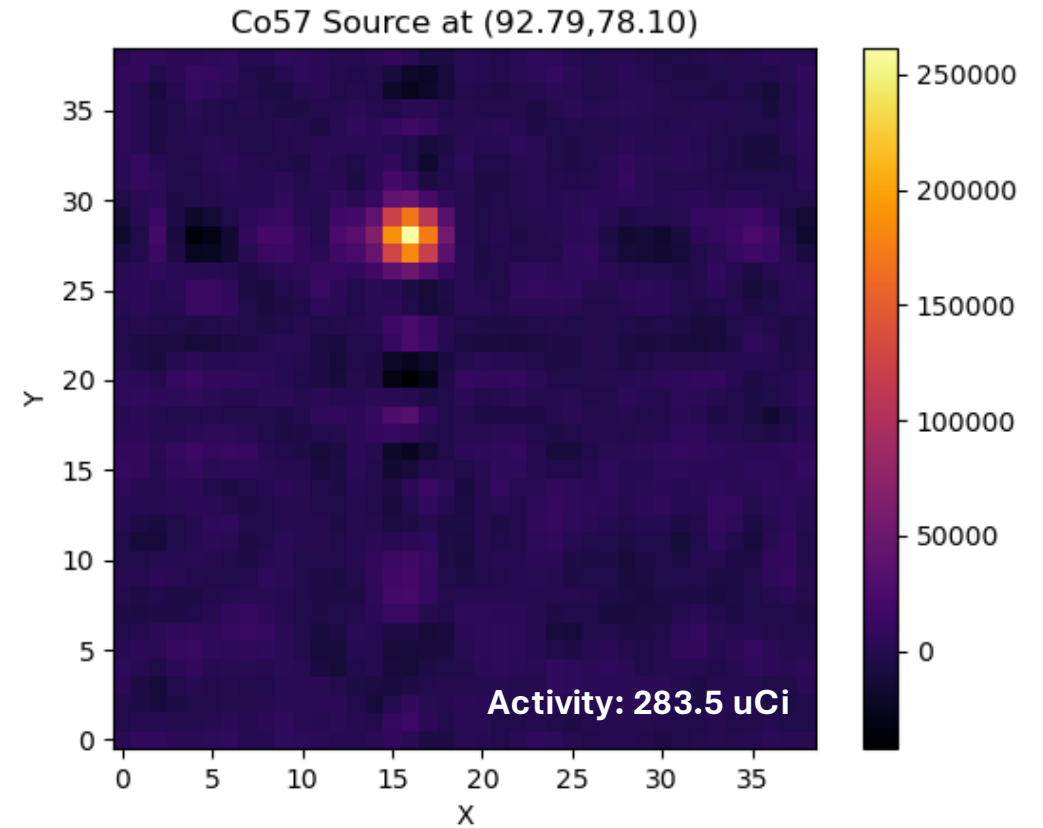
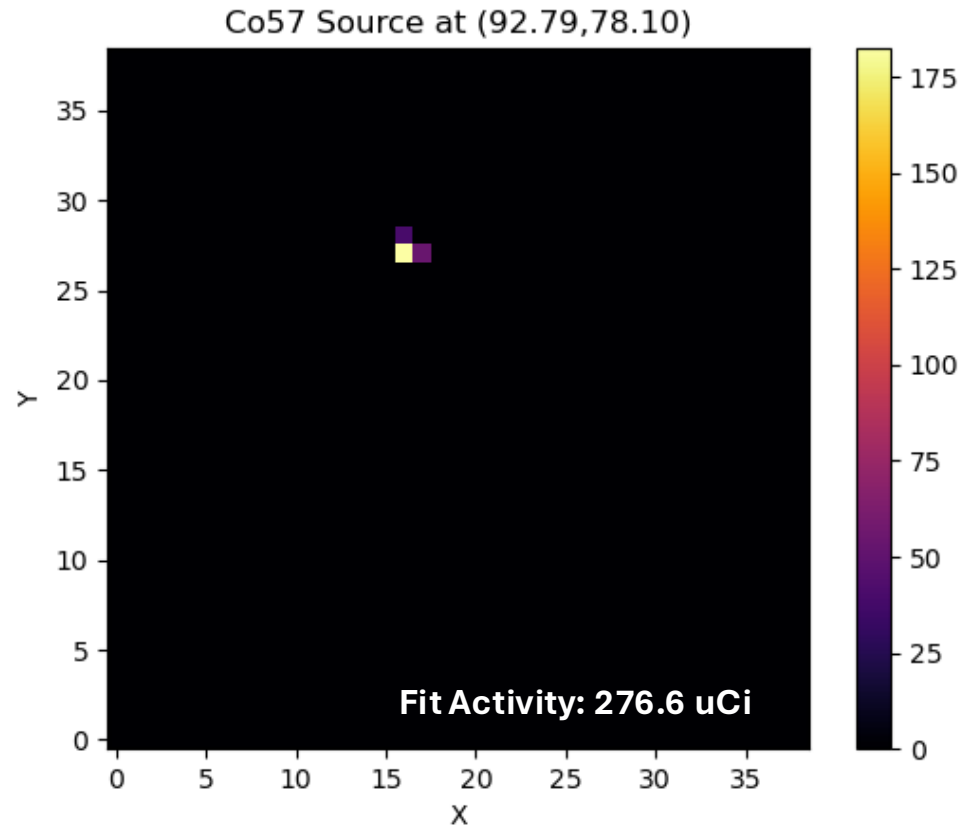
The L1 term seeks to keep the overall scale of the coefficients low (therefore concentrating on the most relevant).

The L2 term helps with feature selection and equal weighting to highly correlated predictors.

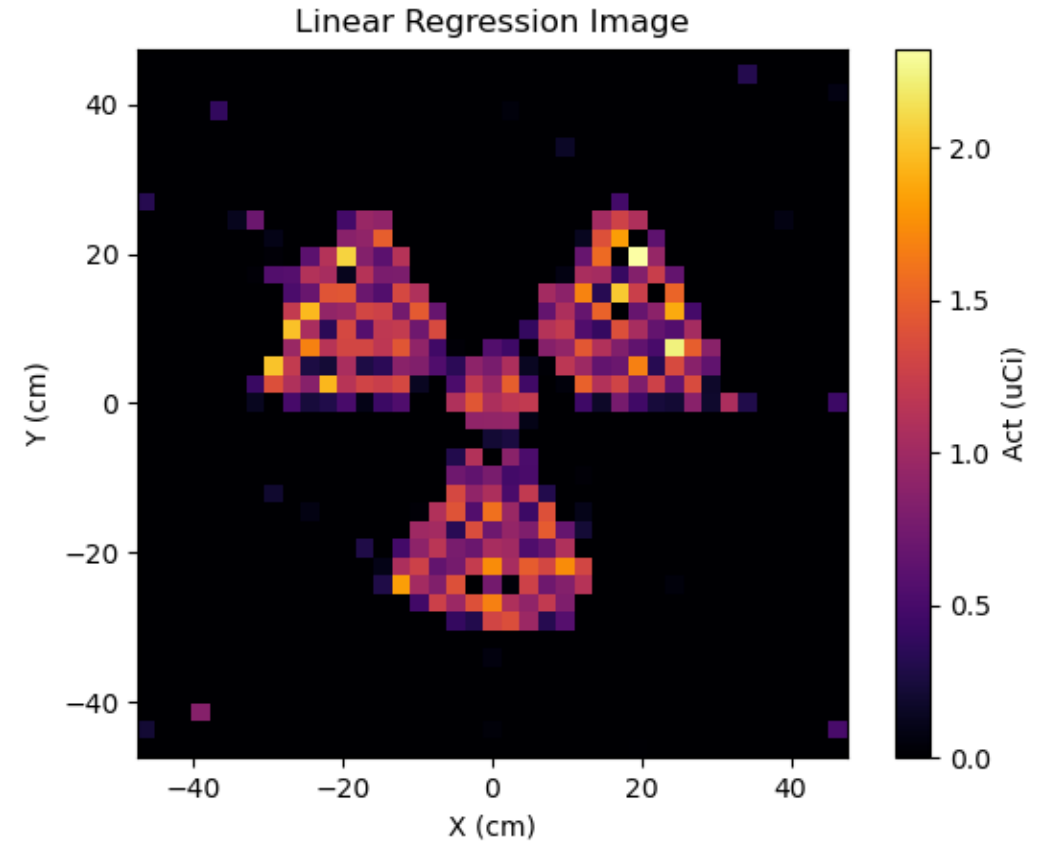
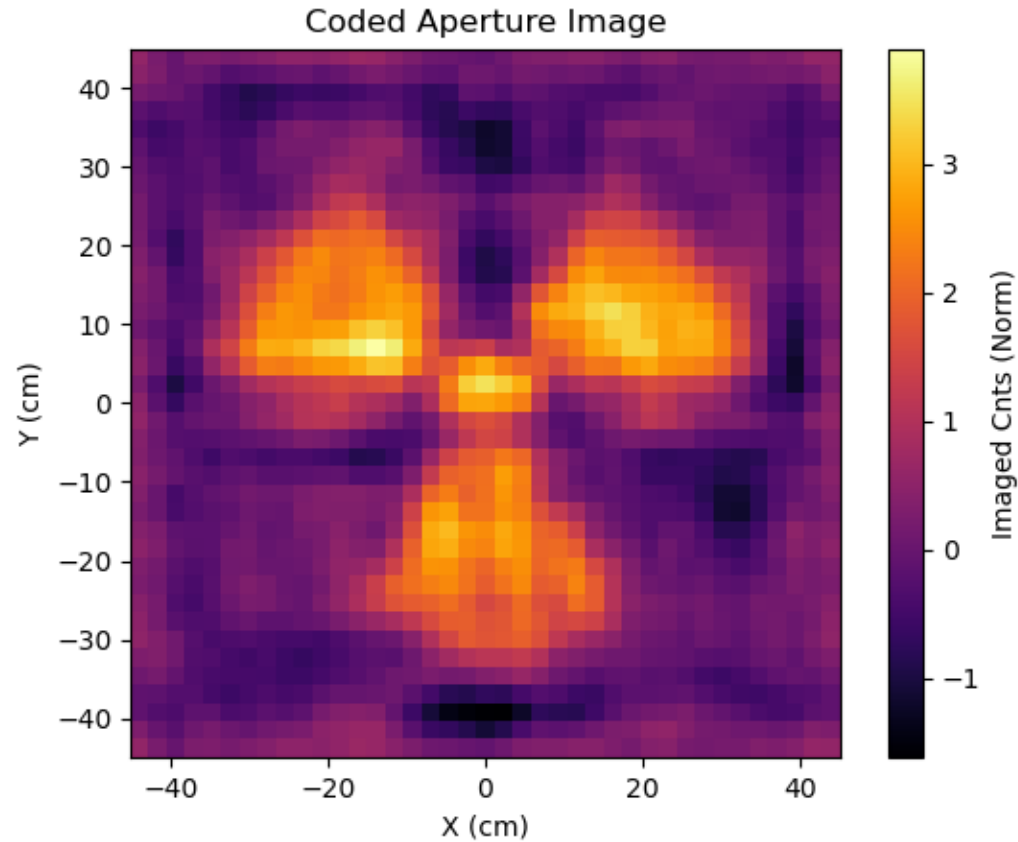
$\rho = 0 \rightarrow$  Ridge Regression

$\rho = 1 \rightarrow$  Lasso Regression

# Calibration Point Source – LR Fit



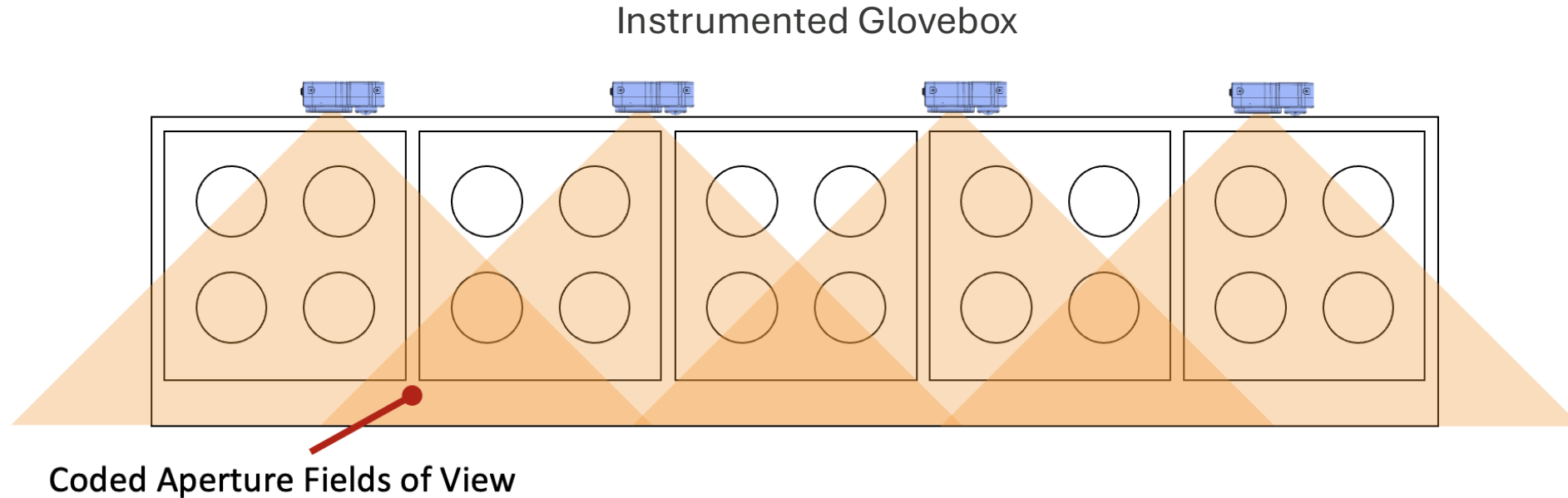
# Extended Source Test



**Fit Activity: 251.72 uCi**

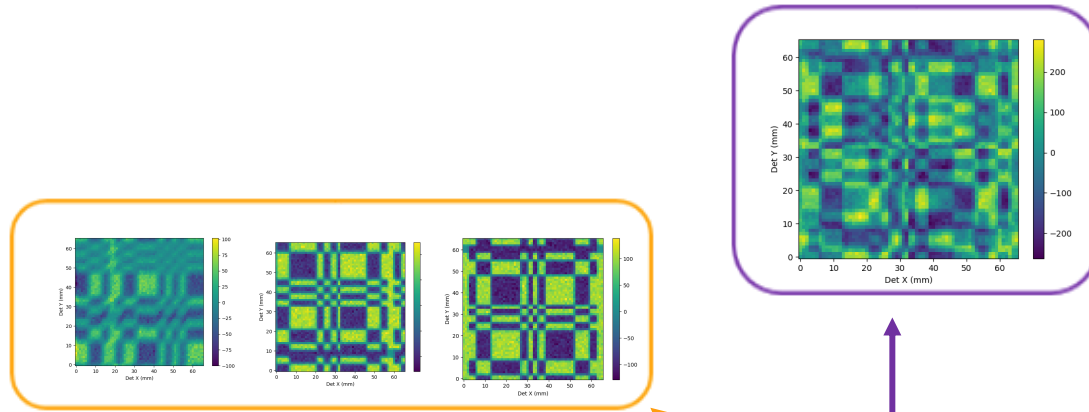
**True: 283.5 uCi**

# Multiple Imager System



- An instrumented glovebox could provide continuous monitoring of material that's being processed.
- Each detector provides its own image – what's the best way to combine this information?

# Extending to Multiple Imagers



$$\min_w \frac{1}{2n_{\text{samples}}} \|Xw - y\|_2^2 + \alpha\rho \|w\|_1 + \frac{\alpha(1-\rho)}{2} \|w\|_2^2$$

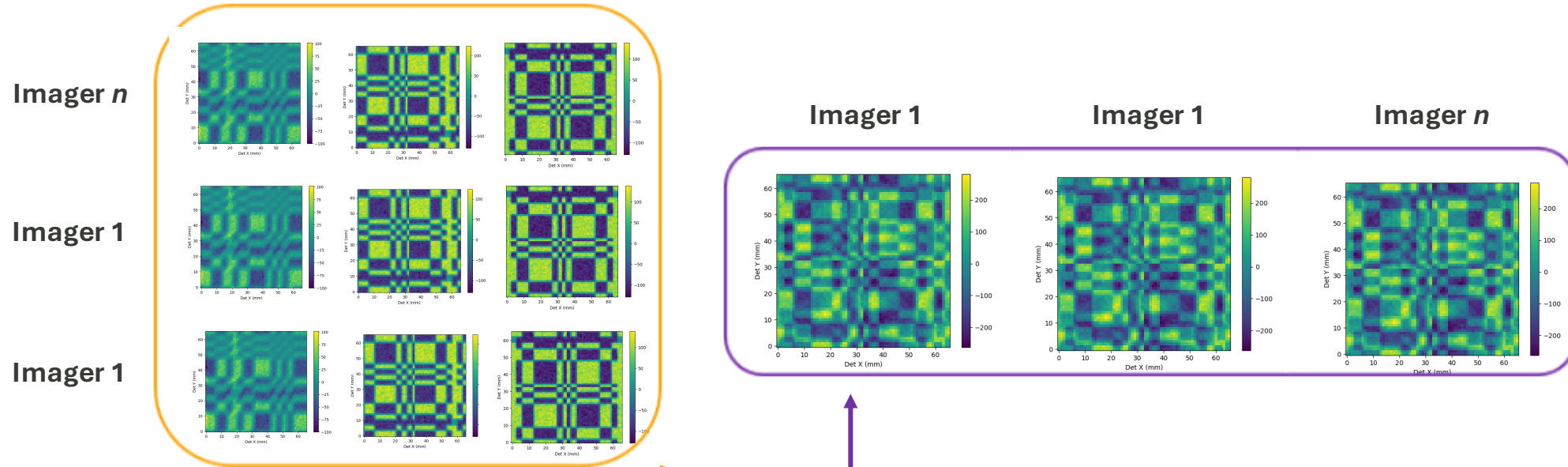
( $M \times B$  matrix)

( $B$ -length vector)

$M$ : Number of locations in basis set

$B$ : Number of bins in subtracted data histogram

# Extending to Multiple Imagers



$$\min_w \frac{1}{2n_{\text{samples}}} \|Xw - y\|_2^2 + \alpha\rho \|w\|_1 + \frac{\alpha(1-\rho)}{2} \|w\|_2^2$$

$(M \times (N \cdot B)$  matrix)

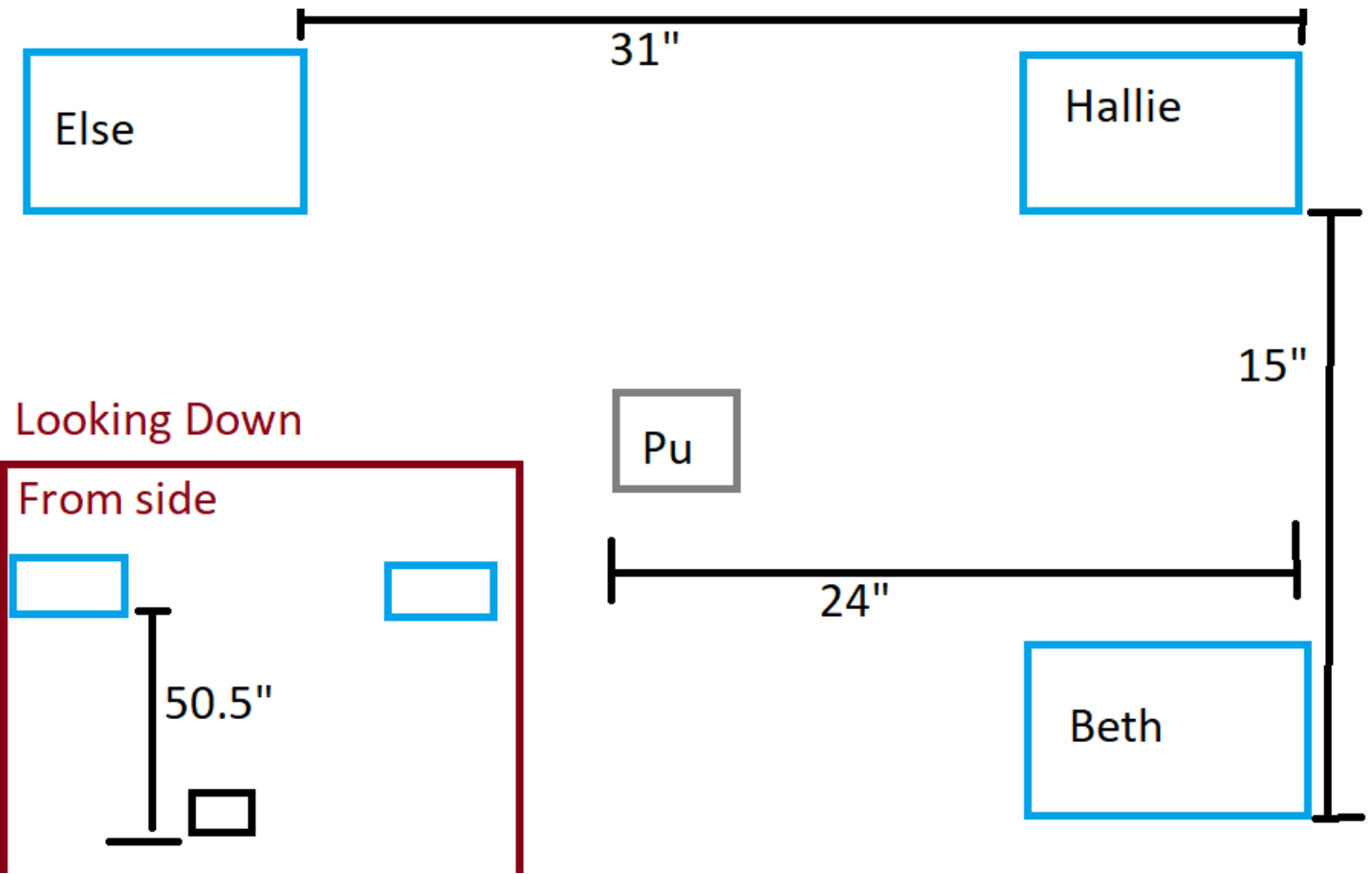
$(N \cdot B)$ -length vector)

$M$ : Number of locations in basis set

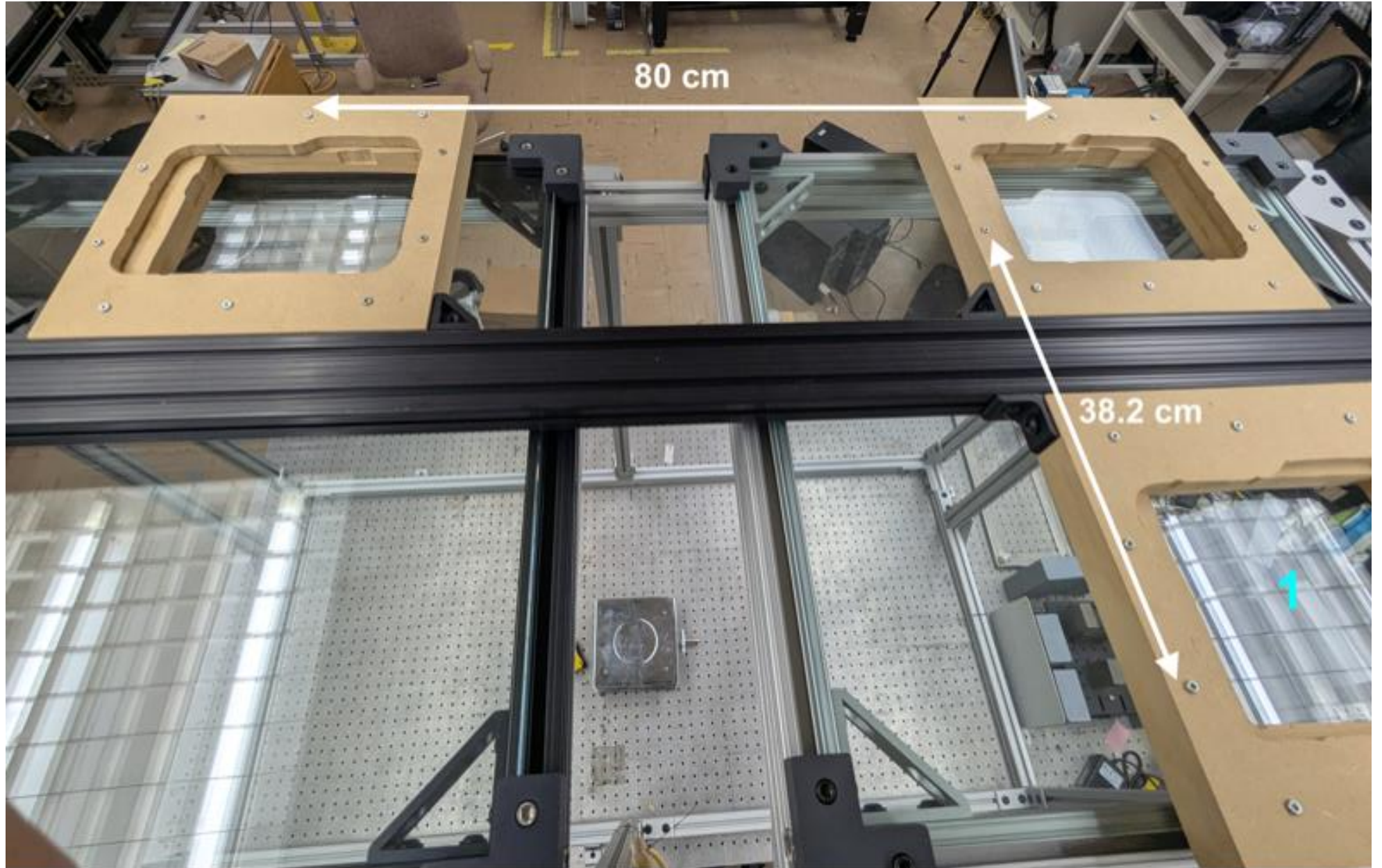
$B$ : Number of bins in subtracted data histogram

$N$ : Number of imagers in system

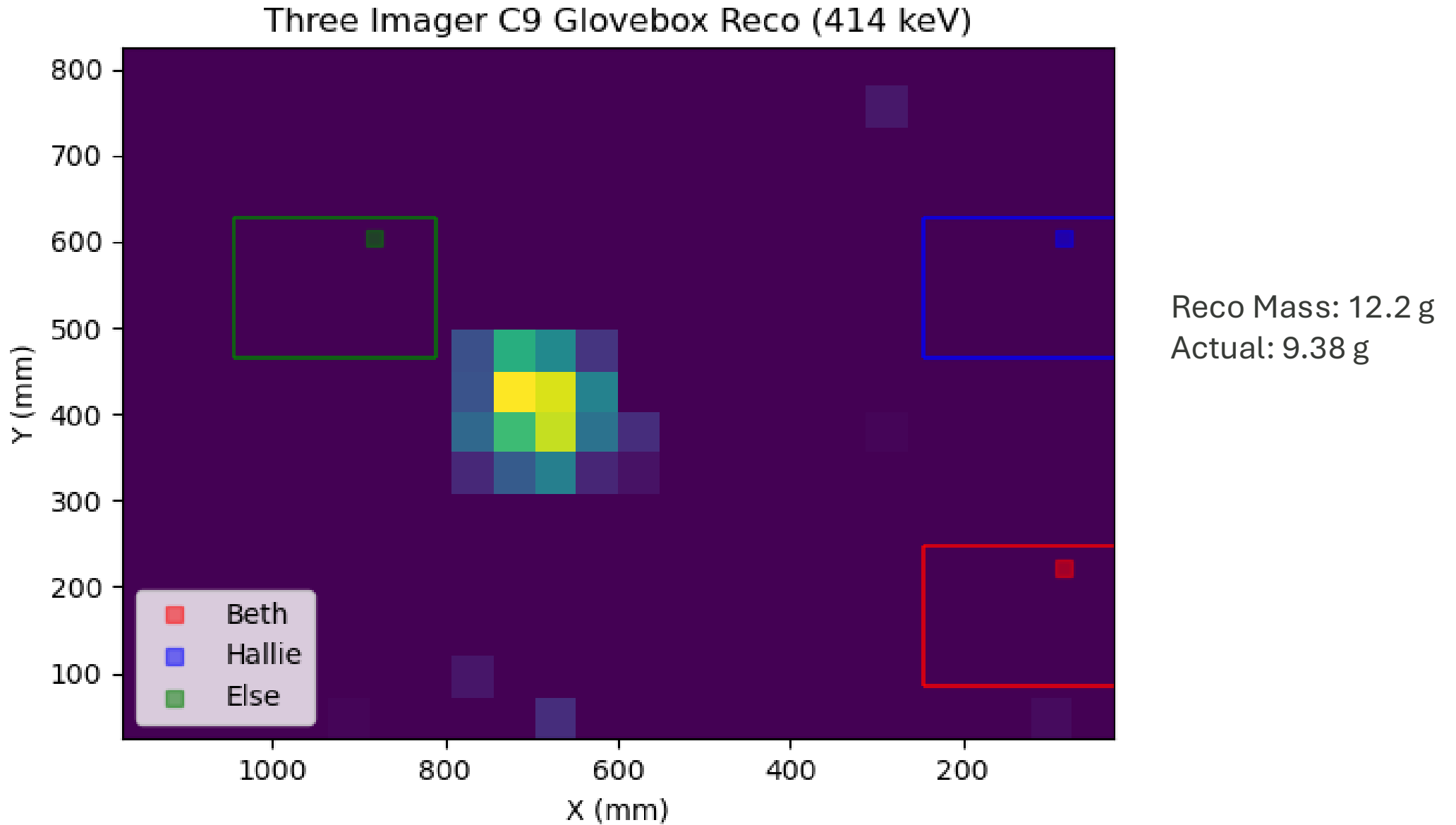
# Three Imager Mock Glovebox



# Three Imager Mock Glovebox

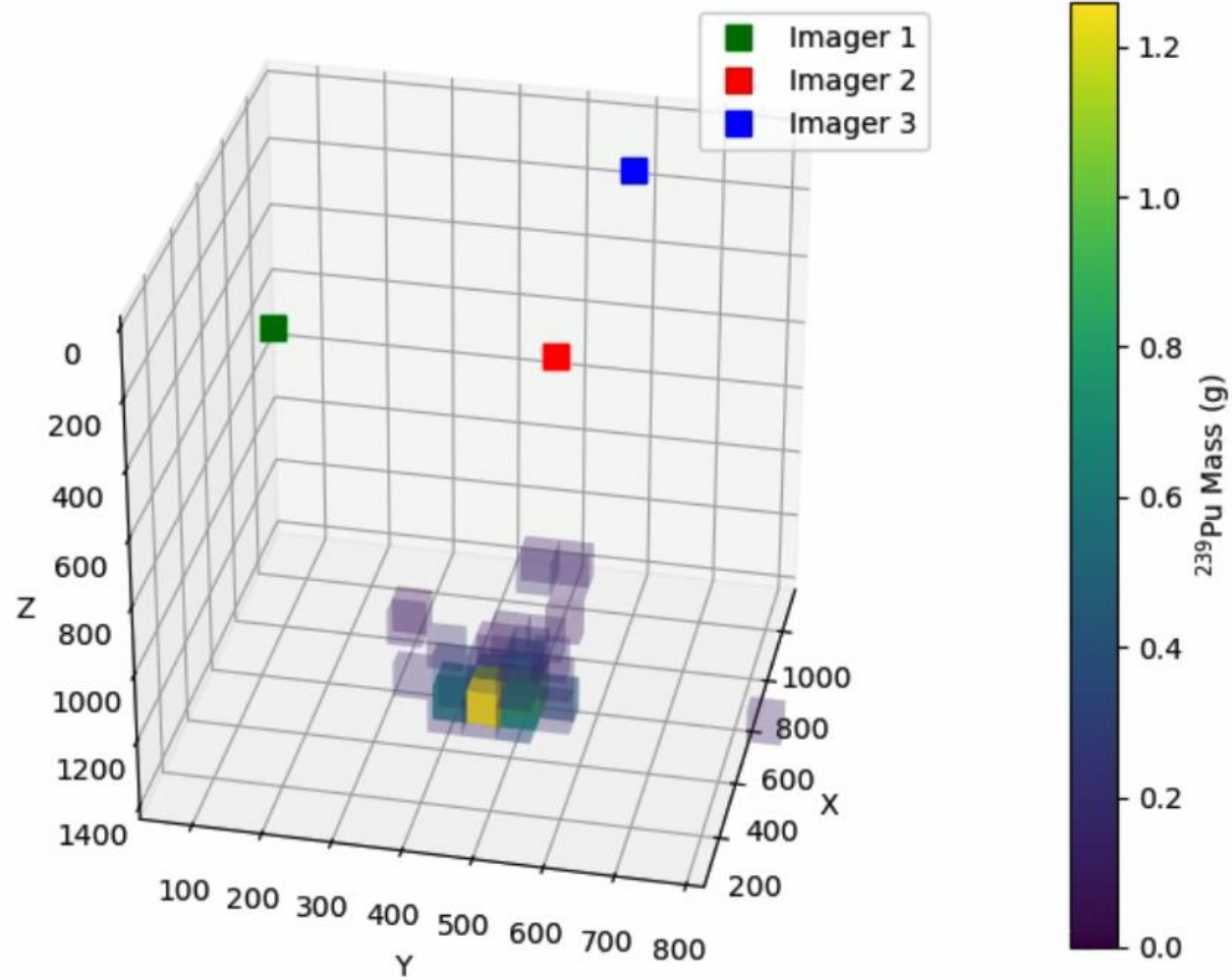


# Multi-Detector Linear Regression Fit

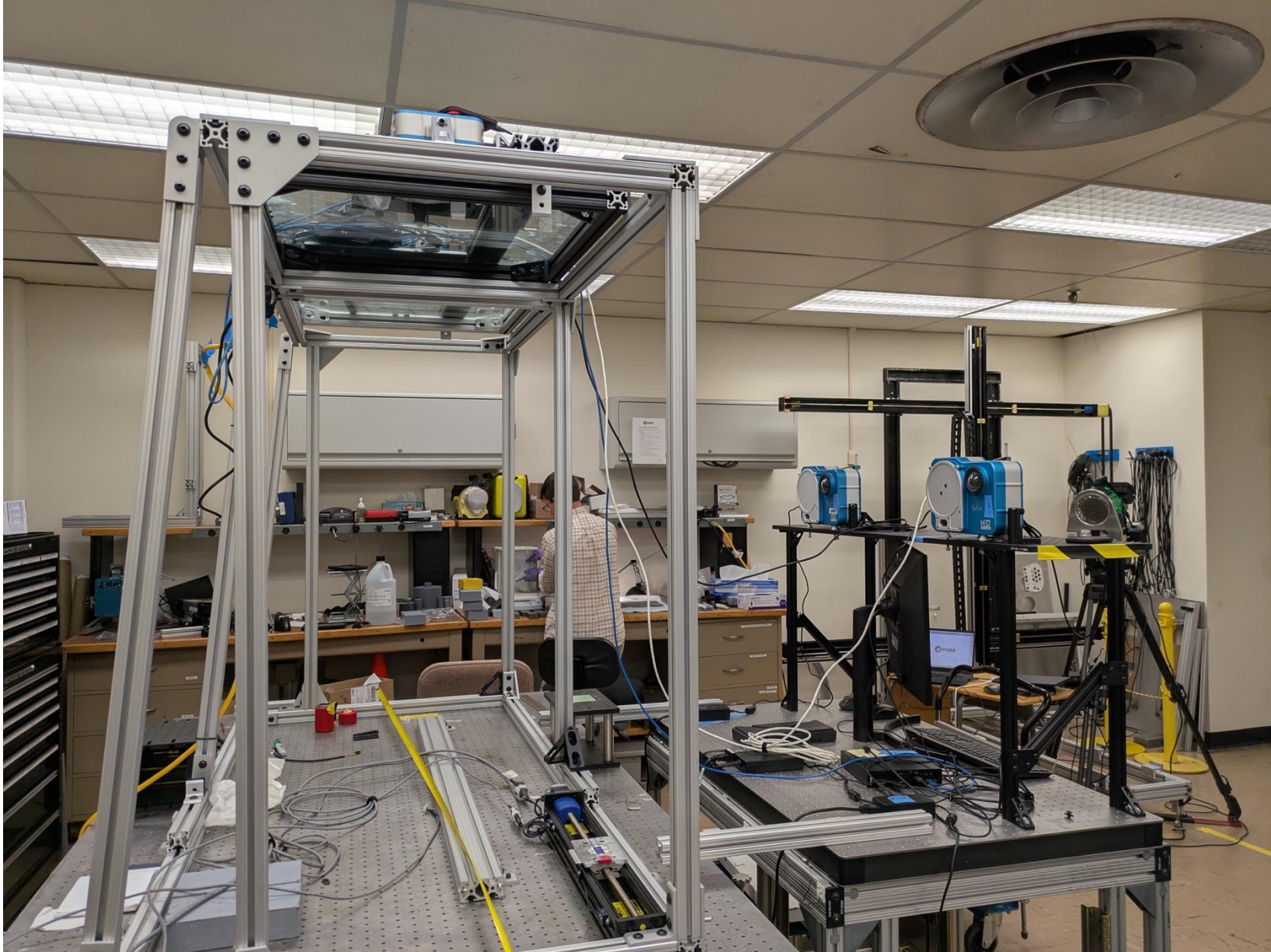


# Multi-Detector Linear Regression Fit

$^{239}\text{Pu}$  Mock Glovebox Reconstruction (414 keV, 11.125 g)



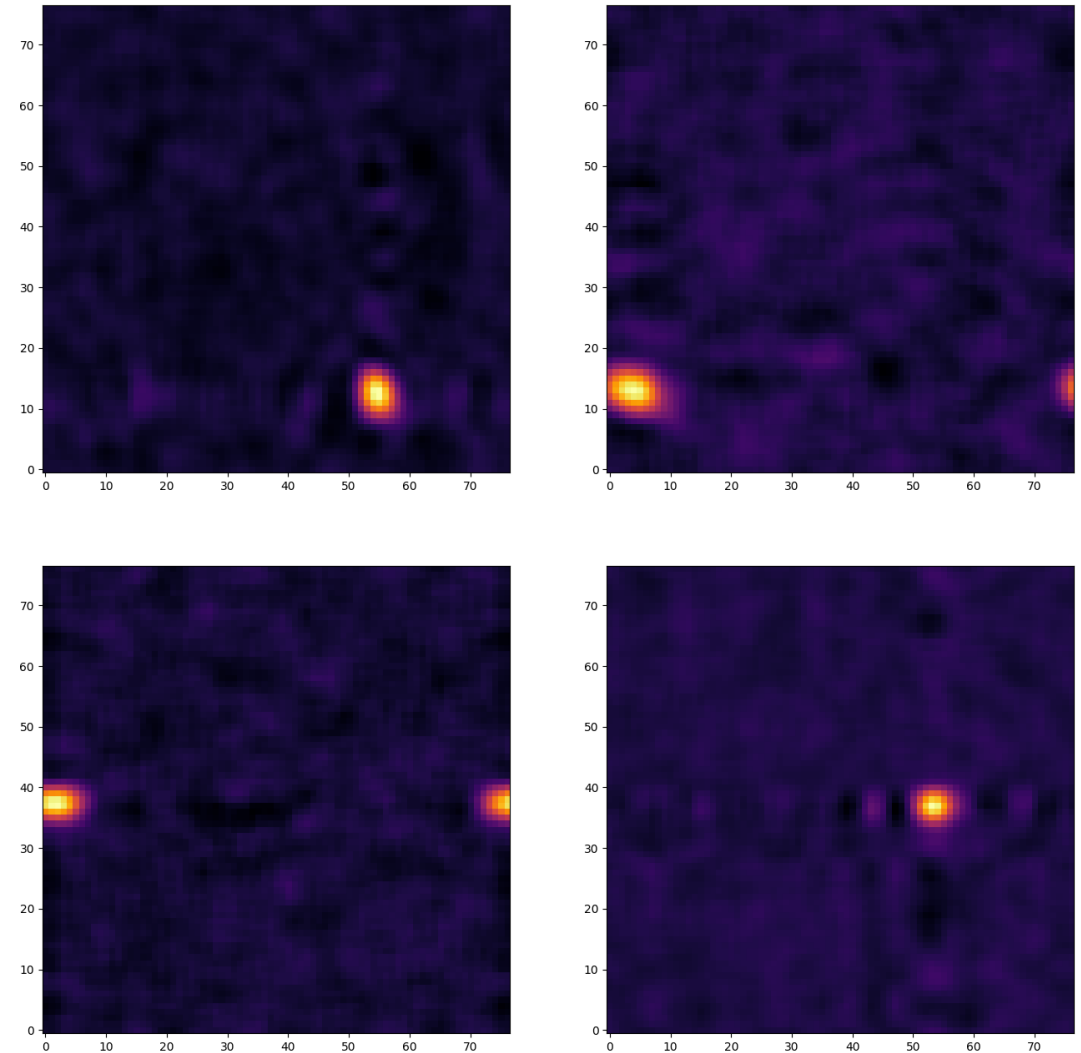
# Ongoing Mockup Measurements



# Ongoing Challenges

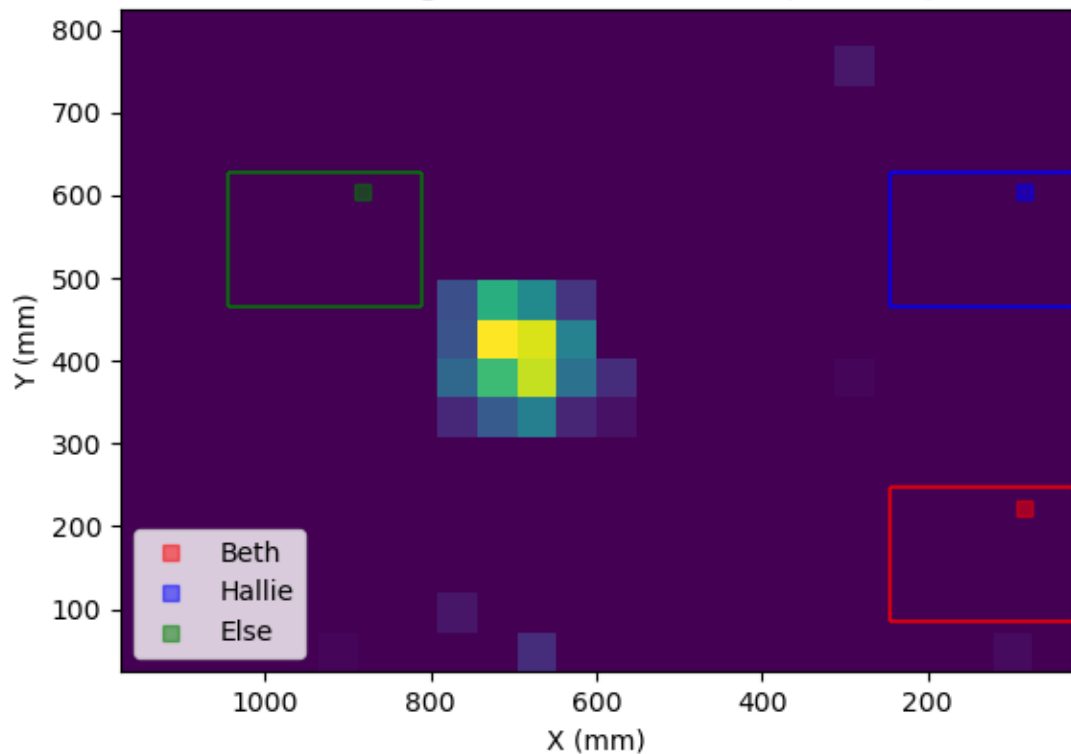
- Inclusion of all idiosyncratic detector behavior – each one has its own imperfections!
- Selection of hyper-parameters. Settling on values that *generally* work well, but adapting data-driven methods from literature has not been simple.
- Establishing performance (minimum detectable amounts, reliable error estimation, etc).
- Incorporation of Compton event information:
  - Use as a regularization term
  - Basis pre-selection tool
  - Direct addition to the basis

Coded-Ap Images (122 keV)



## Full Plane Reco

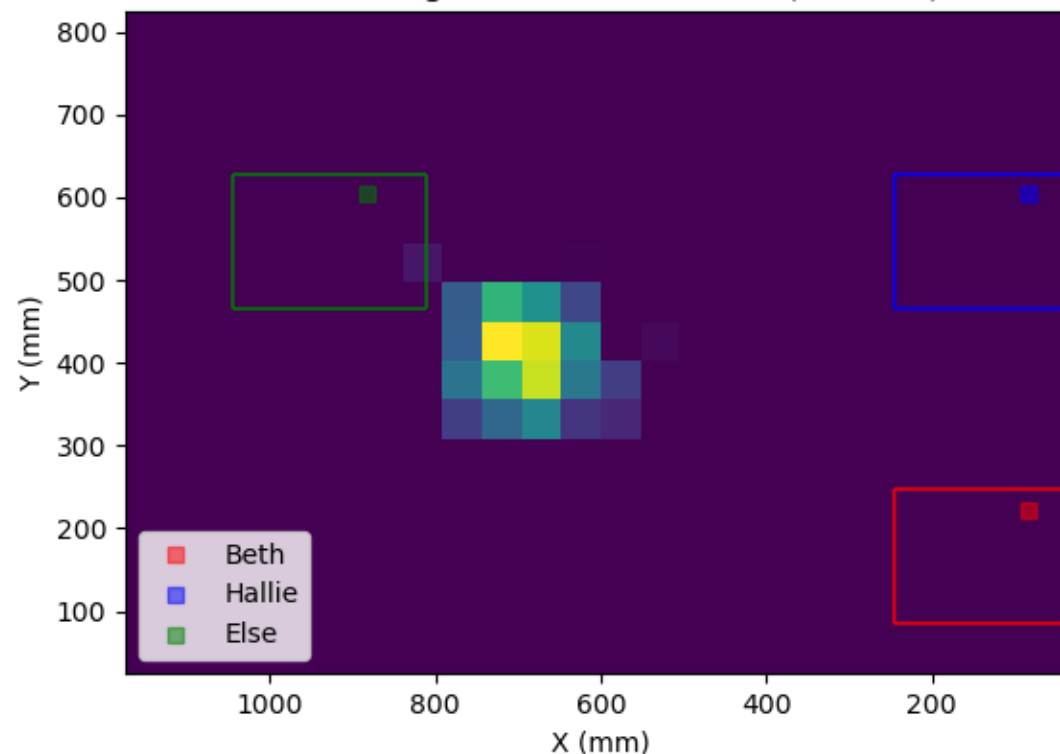
Three Imager C9 Glovebox Reco (414 keV)



Reco Mass: 12.2 g

## Restricted Plane Reco

Three Imager C9 Glovebox Reco (414 keV)



Reco Mass: 13.1 g