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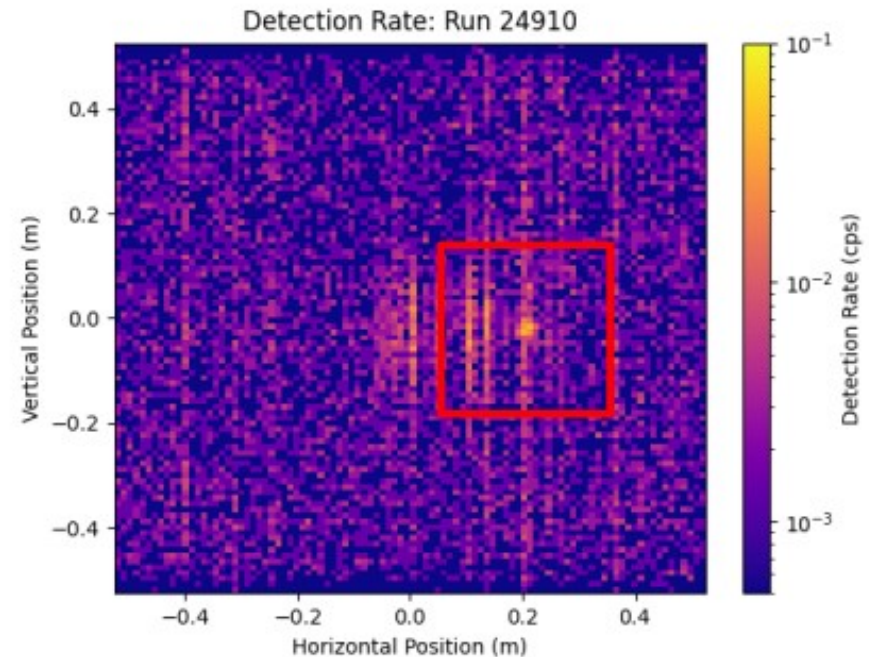
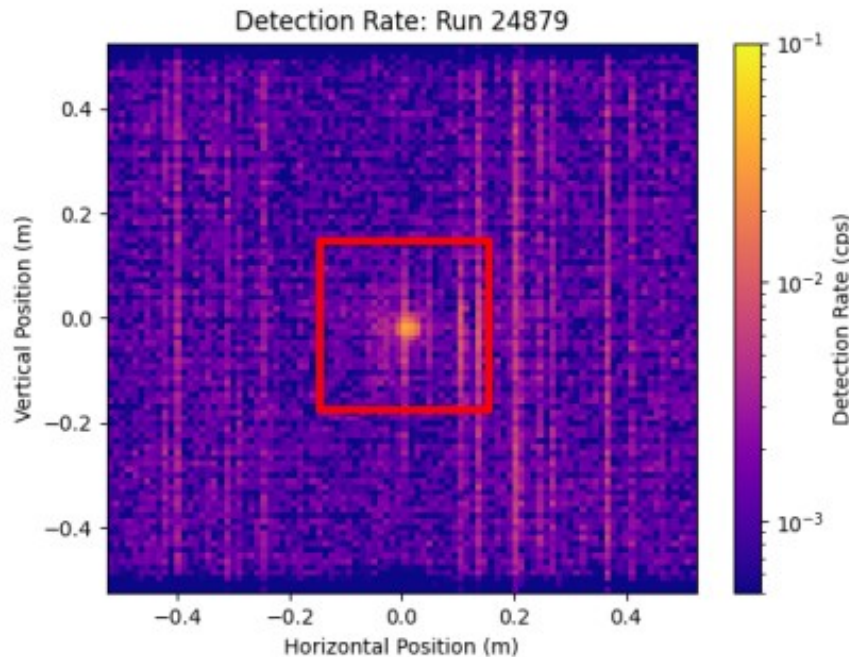
Analyzing GPSANS data from 2021 Experiment

**Estimating fit error using multivariate
parameter sampling, analyzing statistical
effect of $|B|$ on neutron oscillation**

Region of Interest Definition

Size and position of roi defined by centering focus and finding square of size which contains 95% of detections of attenuated beam (24x24cm)

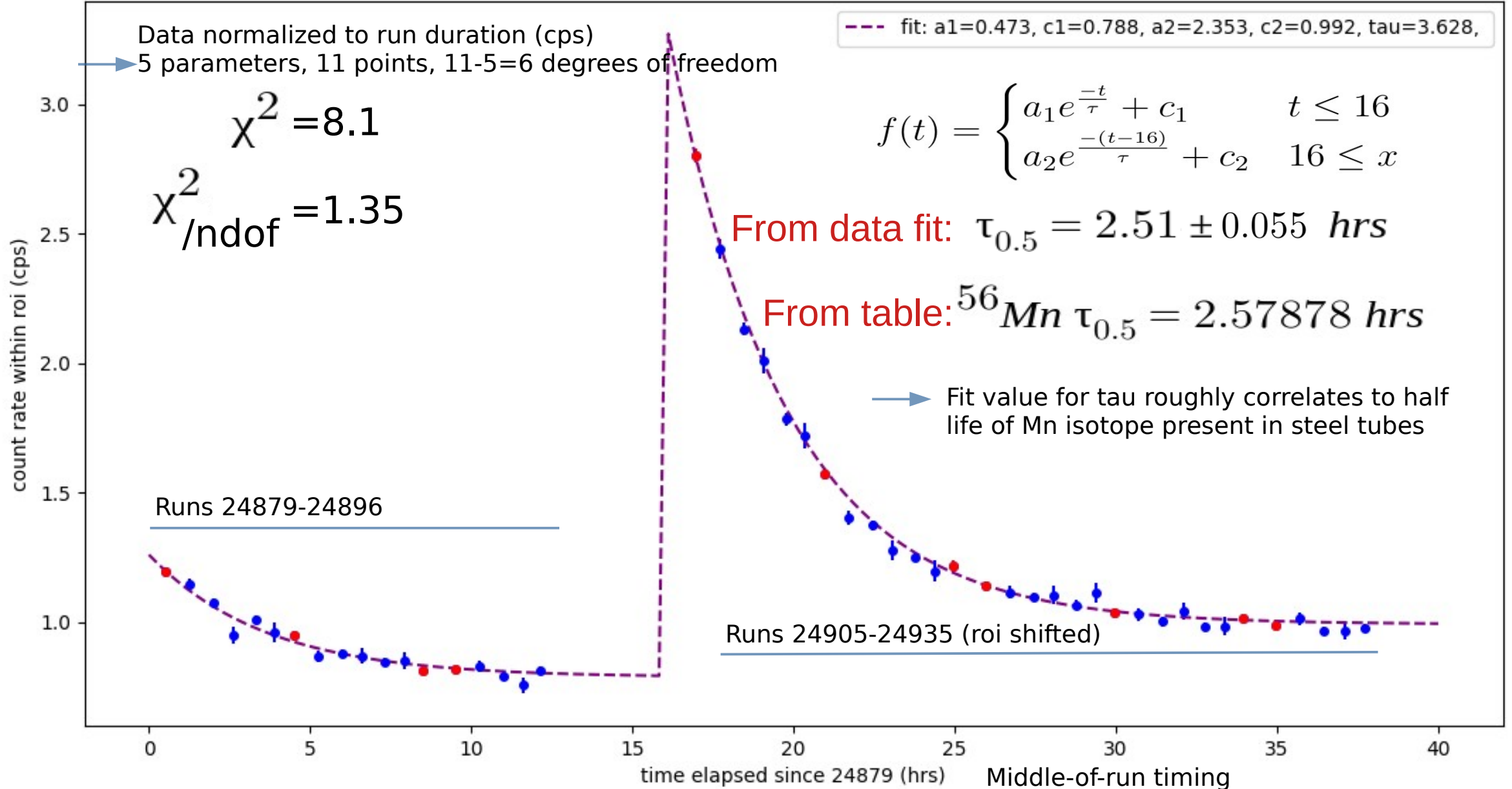
- Detector position shifted ~20cm between runs 24902-24904



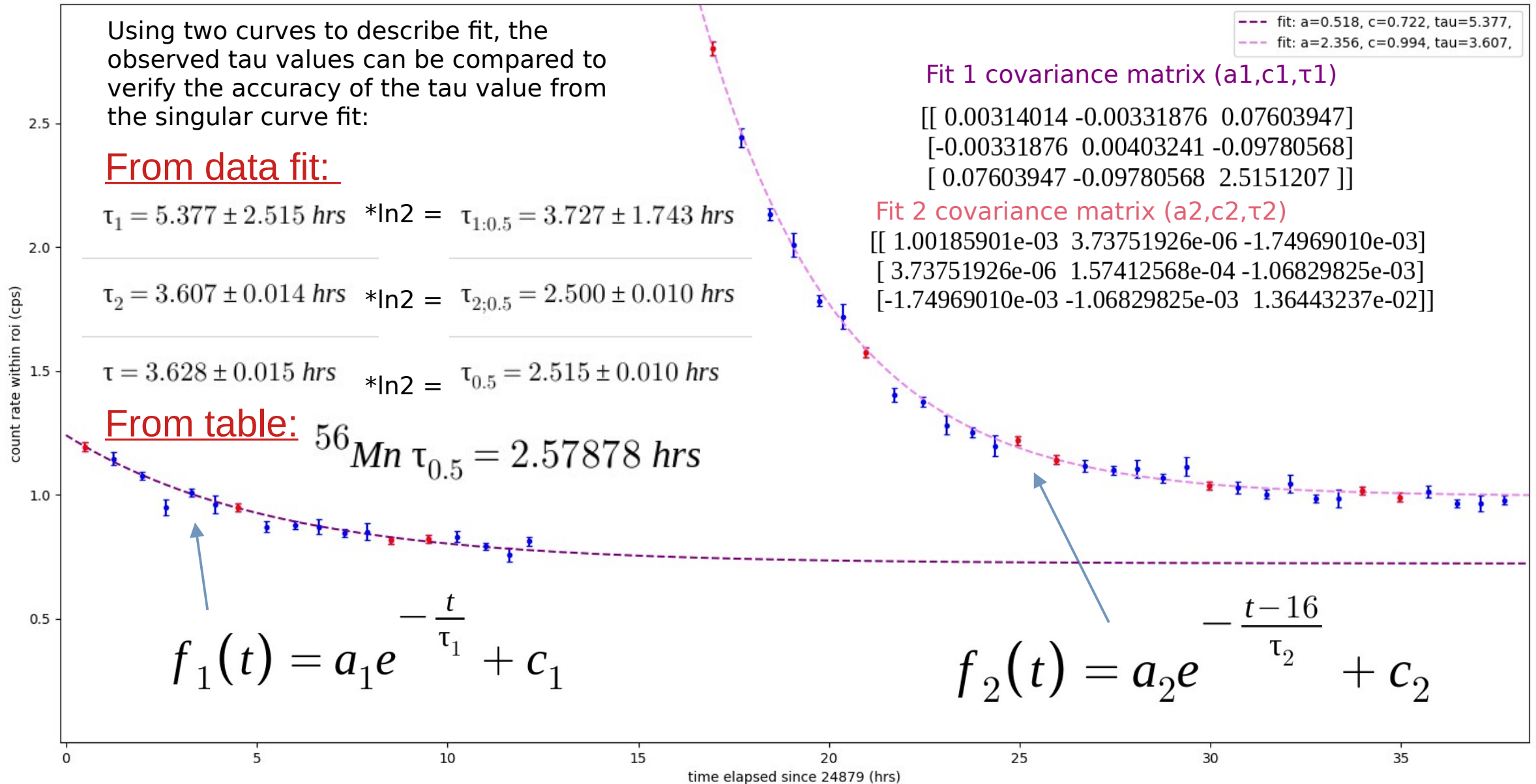
- Total counts per run within these roi were then recorded and plotted

Curve fitting to counts within ROI

Red runs have field $|B|=0$, curve is fit to red points (assumes $|B|=0$ has no effect)

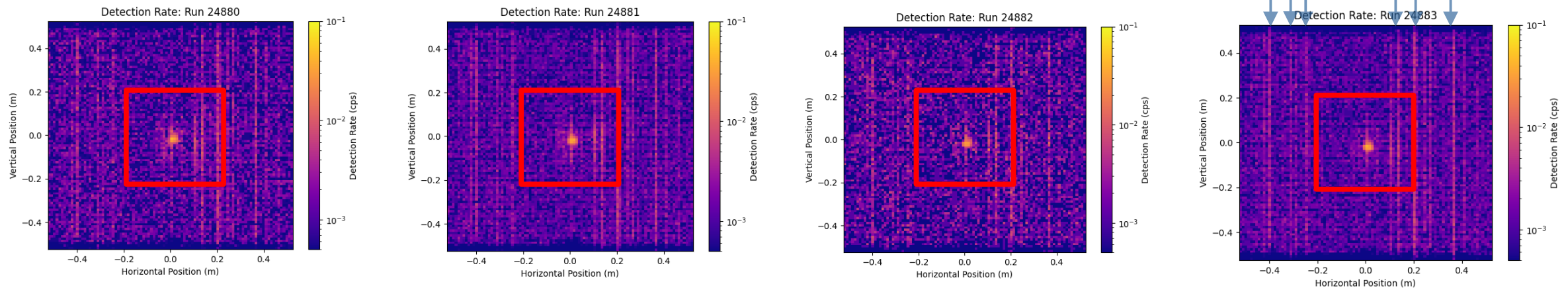


Resilience of fit

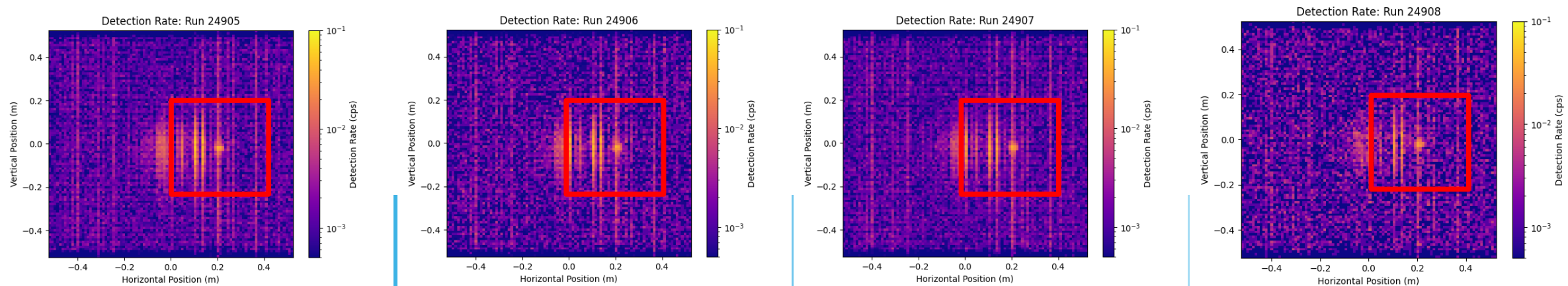


Regions of Interest

- Different ROIs include different tubes, some tubes are more noisy than others, could explain difference in background value (c1,c2) of fit
- First Sequence (runs 24879-24902)**



Second Sequence (runs 24904-24935), roi shifted 20cm



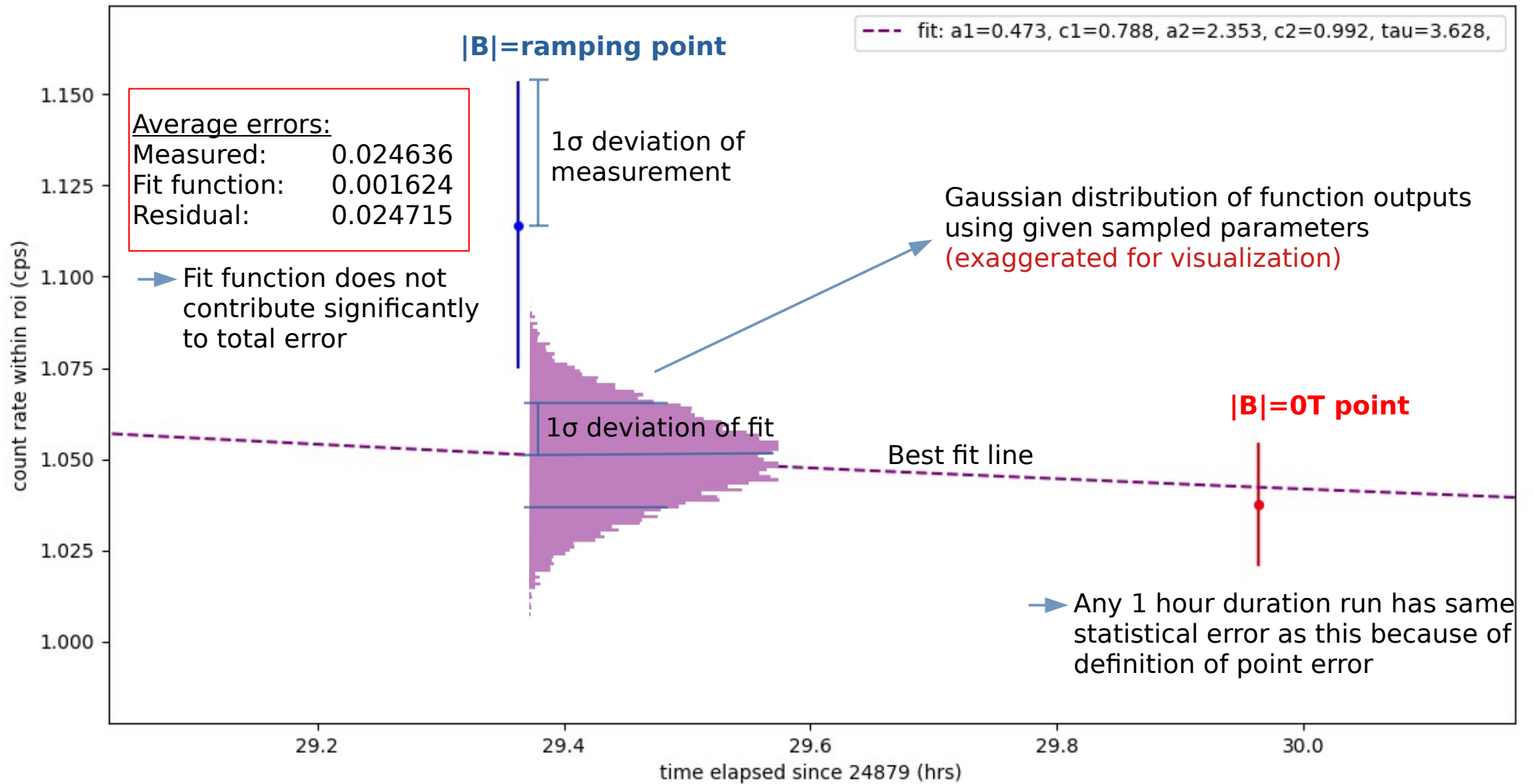
Covariance Matrix for $|B|=0$, 5 parameters fit

	a1	c1	a2	c2	tau
a1	9.74E-04	-3.31E-04	-3.24E-05	-2.02E-05	2.57E-04
c1	-3.31E-04	2.26E-04	6.71E-05	4.18E-05	-5.33E-04
a2	-3.24E-05	6.71E-05	1.12E-03	4.87E-07	-1.93E-03
c2	-2.02E-05	4.18E-05	4.87E-07	1.78E-04	-1.20E-03
tau	2.57E-04	-5.33E-04	-1.93E-03	-1.20E-03	1.53E-02

- Covariance matrix shows correlation between variables, diags show standard deviation of each variable
- symmetric positive definite matrix

$$f(t) = \begin{cases} a_1 e^{\frac{-t}{\tau}} + c_1 & t \leq 16 \\ a_2 e^{\frac{-(t-16)}{\tau}} + c_2 & 16 \leq x \end{cases}$$

Visualization of Sampling Process



Using cov. Matrix to find fit error

(1) For each time value, find estimated countrate using best fit function $f(t)$ with **optimal params**

(2) take 5d correlated gaussian sample for params using **cov**, find $f(t, p')$ estimated countrate given those params

(3) find difference between best fit estimate (1) and sampled params estimate (2)

(4) repeat steps (2)-(3) 100,000 times, find standard deviation of difference found in (3)

→ standard deviation = error for $f(t)$ found in (1)

$$f(t) = \begin{cases} a_1 e^{\frac{-t}{\tau}} + c_1 & t \leq 16 \\ a_2 e^{\frac{-(t-16)}{\tau}} + c_2 & 16 \leq x \end{cases}$$

- **Error for points = standard deviation of fit value for each point**
- **Using numpy function:**
`np.random.mult(params, cov matrix)`
 - **Samples params for fit' function given covariance matrix from scipy fit**

Error propagation for correction

→ *measured* − *fitted* = *residual rate*

$$R_m - R_f = R_r \quad (\text{Total measured} - \text{background effect}) = \text{isolated } |B| \text{ effect we are looking for}$$

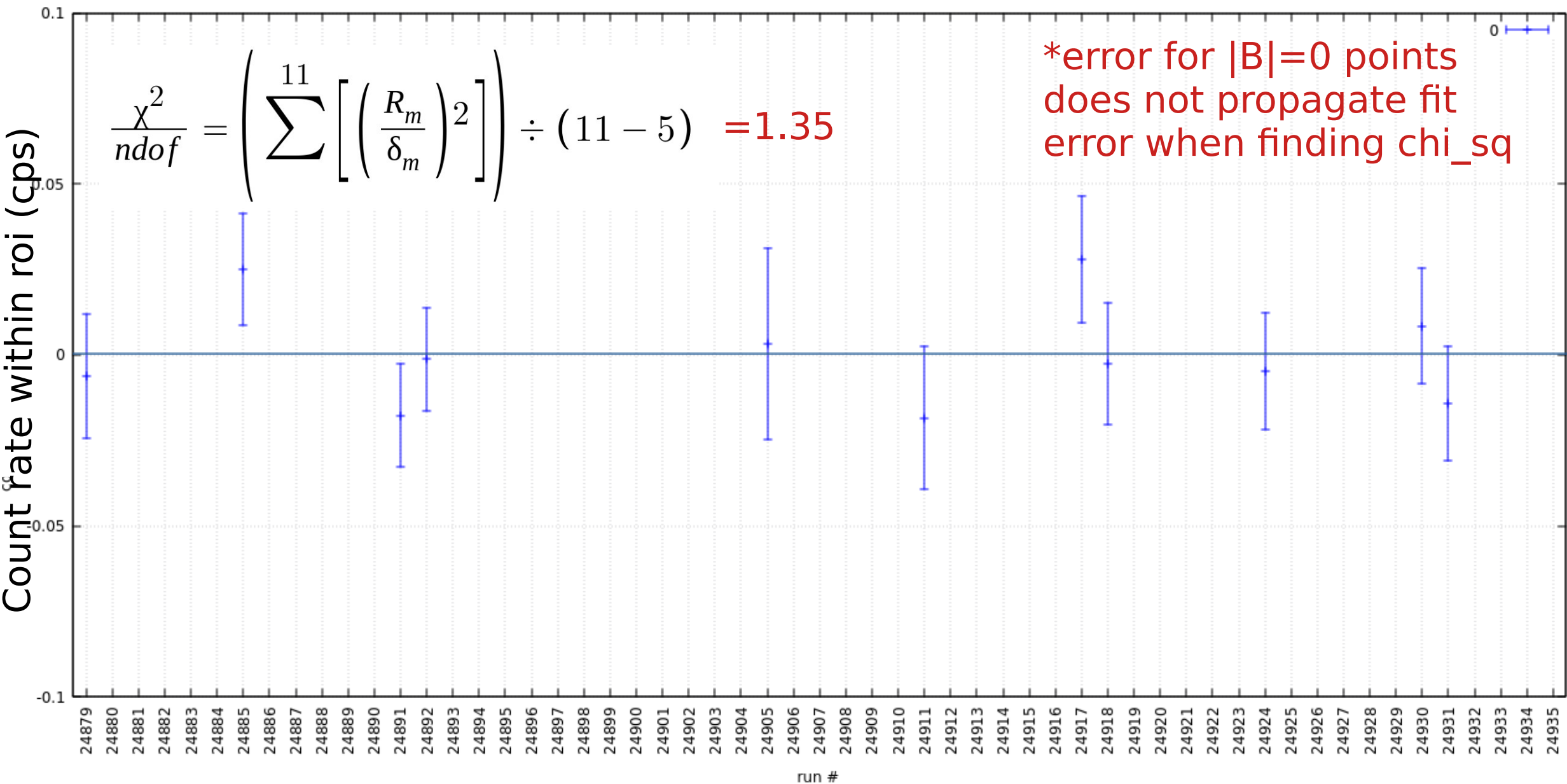
→ $\delta_m = \frac{\sqrt{N}}{\Delta t}$ Error for countrate value defined as sqrt(total counts within roi)/ total duration of run

$\delta_f =$ Error for fit defined as 1 standard deviation of fit' value for each point, and fit'(t) calculated with parameters sampled from given covariance matrix

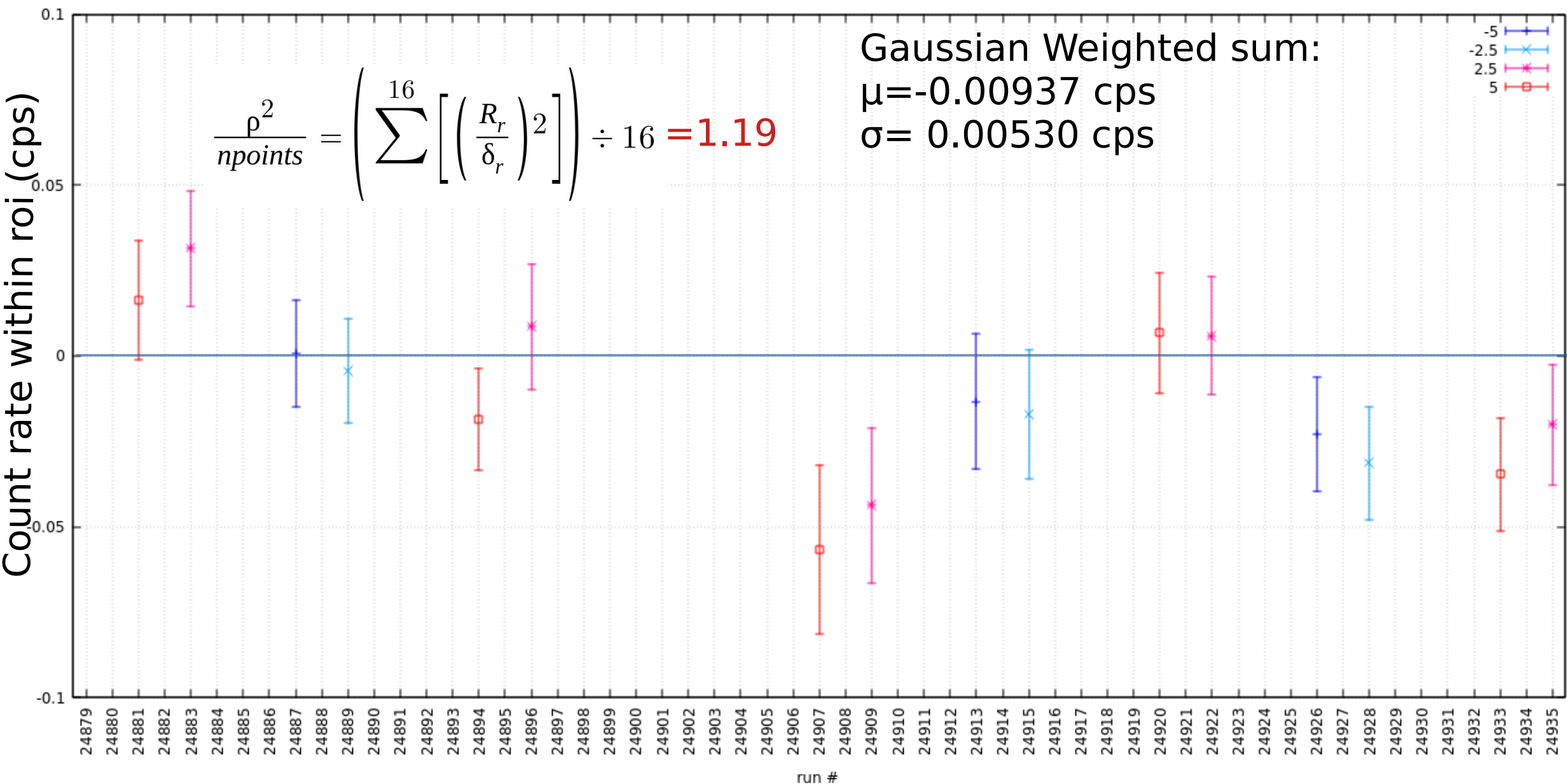
→ $\delta_r = \sqrt{\delta_m^2 + \delta_f^2}$ Error for residual rate found by adding component rates in quadrature

→ $R_r = (R_m - R_f) \pm \sqrt{\delta_m^2 + \delta_f^2}$ **Final value for residual rate**

Residue of |B|=0 points : finding chi^2

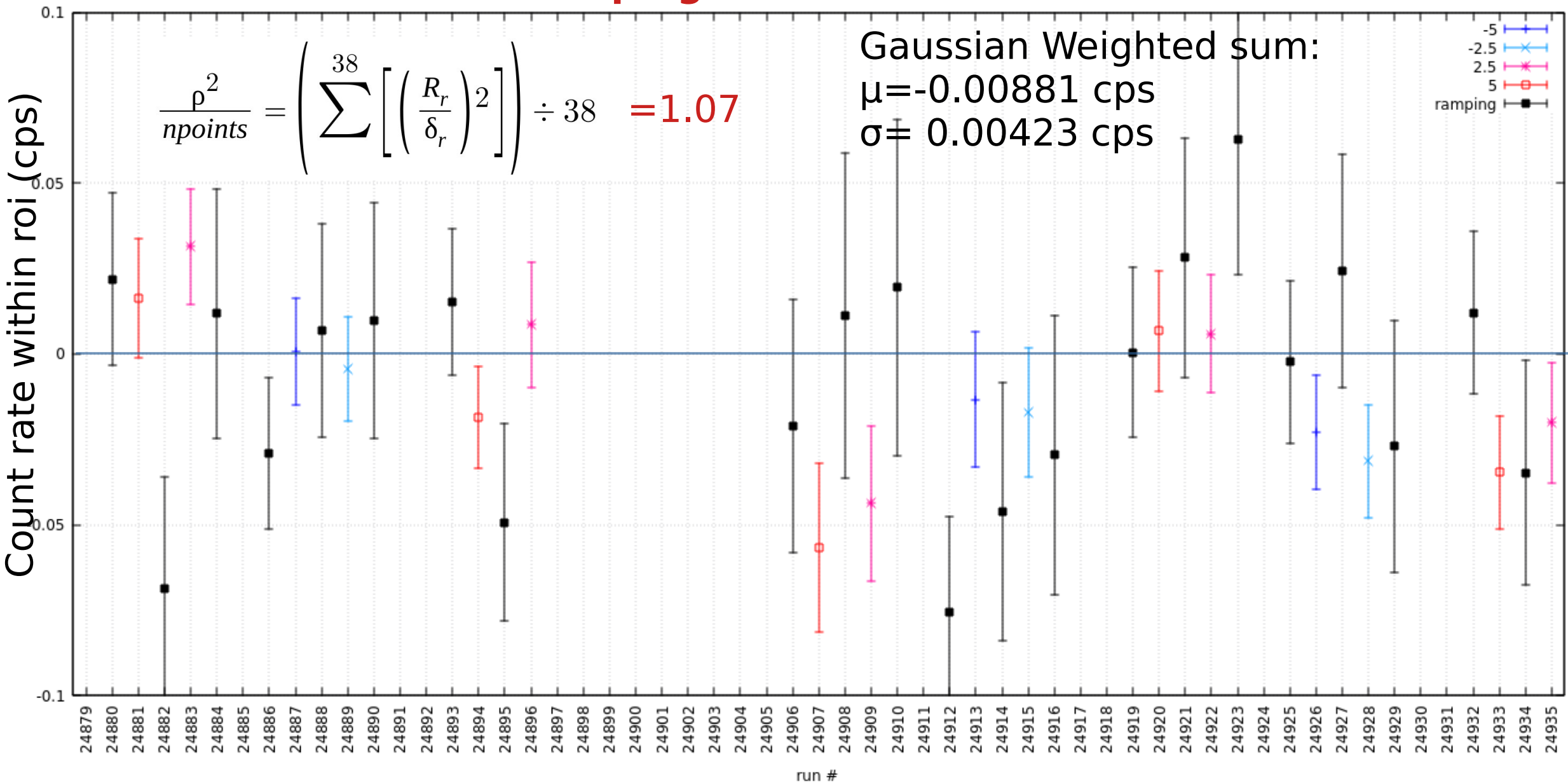


Residue with propagated error for runs |B|=-5,-2.5,2.5,5

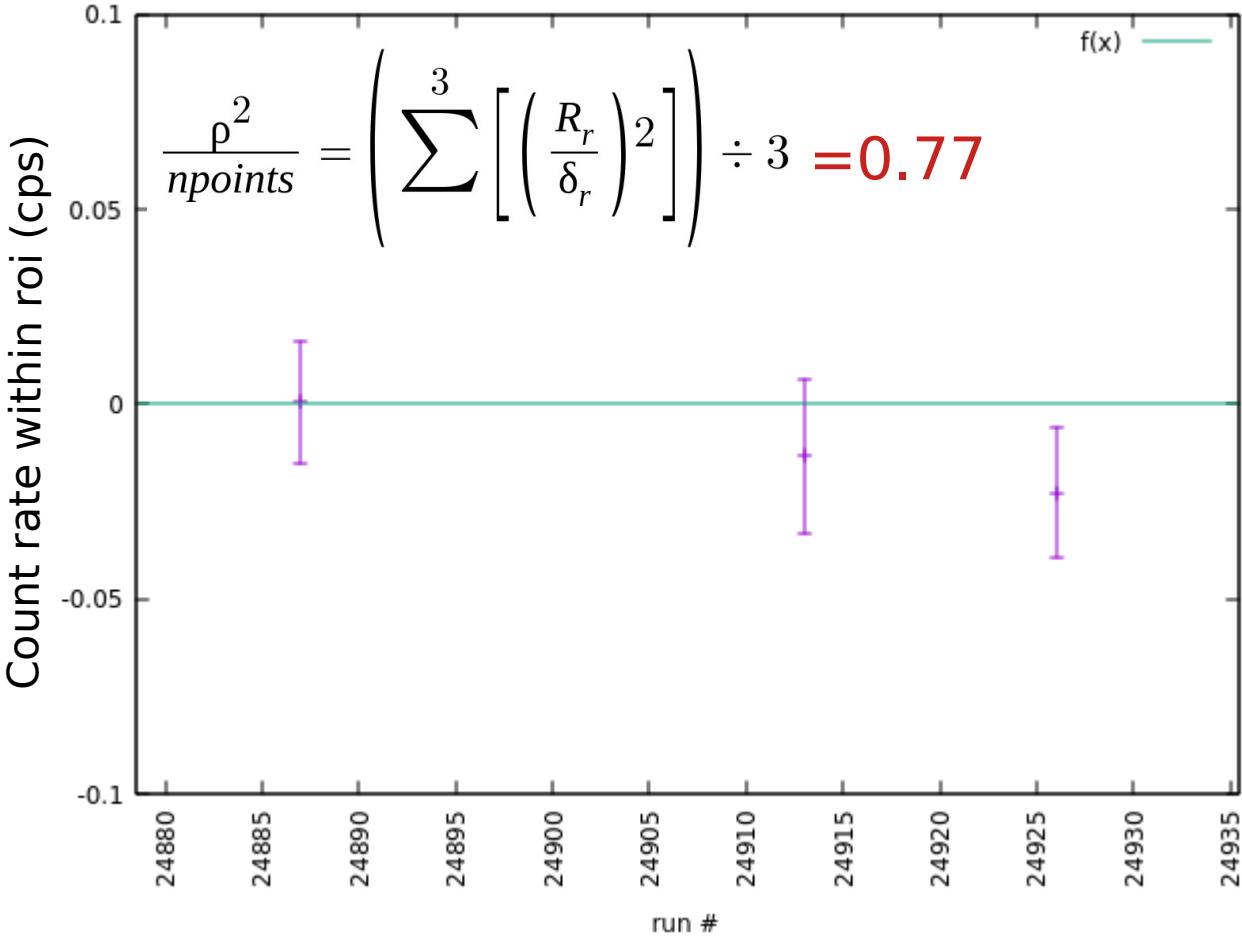


Residue with final error for runs $|B| \neq 0$

***Ramping runs in black**



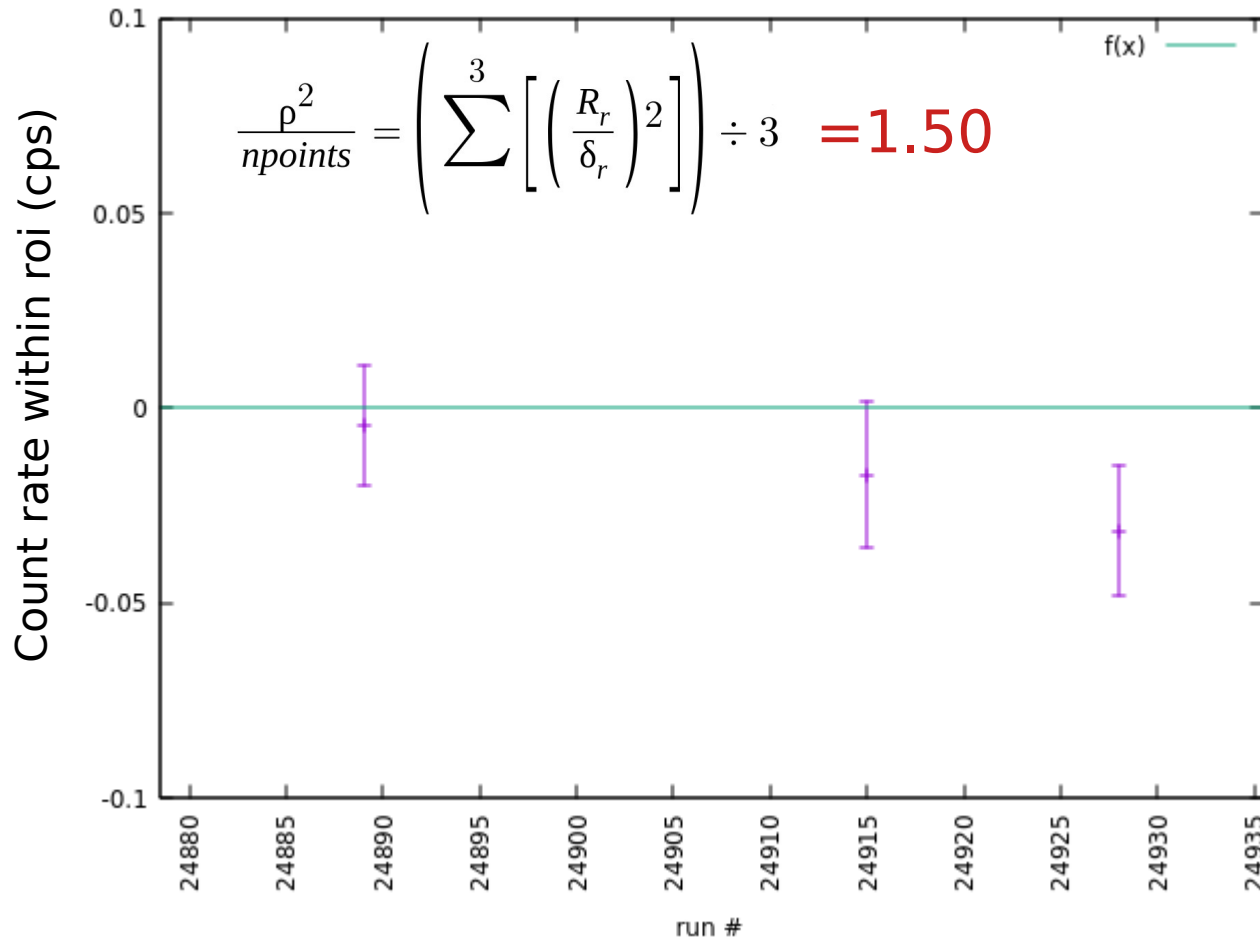
(residue per point) **|B|=-5.0T**



Gaussian Weighted sum:
 $\mu = -0.01147$ cps
 $\sigma = 0.01188$ cps

#run	corrected counts ▶	error	B
24887	0.000595614738	0.0156598062	-5
24913	-0.0133341242	0.0198329428	-5
24926	-0.0227873336	0.0167062451	-5

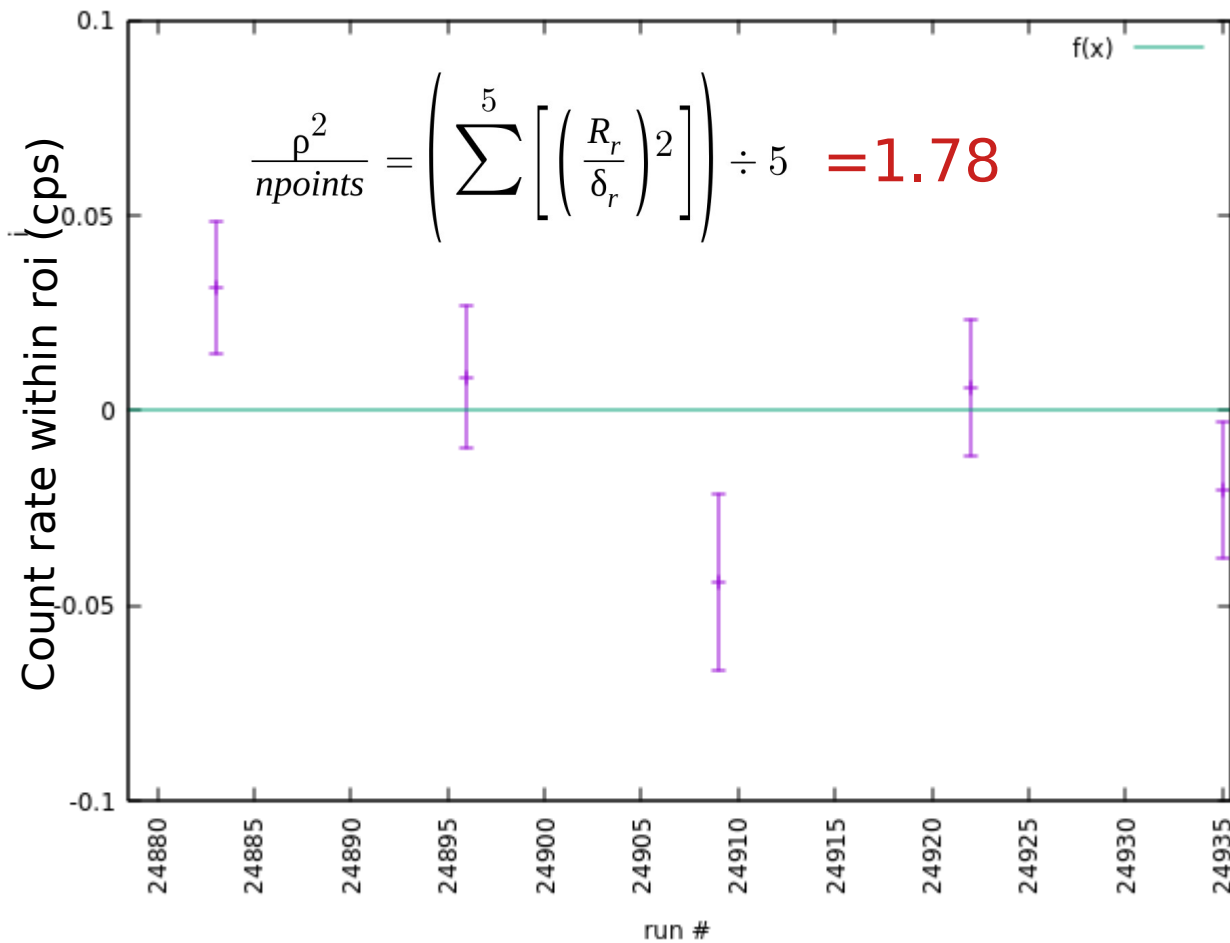
|B|=-2.5T



Gaussian Weighted sum:
 $\mu = -0.01731$ cps
 $\sigma = 0.01180$ cps

#run	corrected counts	error	B
24889	-0.00433777537	0.0153618211	-2.5
24915	-0.017016683	0.0188619339	-2.5
24928	-0.0313999617	0.0165443089	-2.5

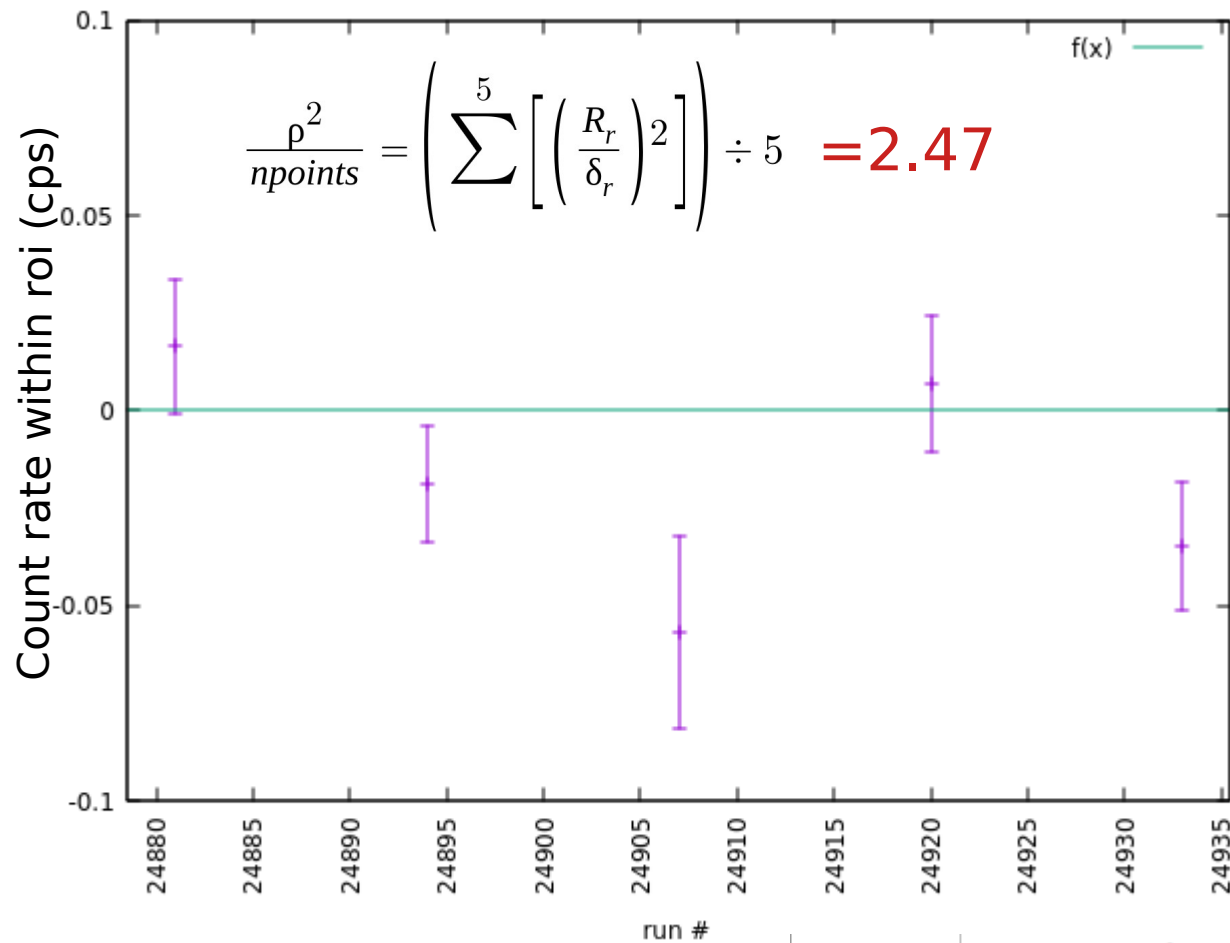
$$|B|=2.5T$$



Gaussian Weighted sum:
 $\mu=0.00138$ cps
 $\sigma=0.00977$ cps

#run	corrected counts within <u>roi</u>	error	B
24883	0.0314349476	0.0168019511	2.5
24896	0.00863990393	0.0183027262	2.5
24909	-0.0437128771	0.0226577458	2.5
24922	0.00585317692	0.0172674944	2.5
24935	-0.0201436788	0.0175670429	2.5

|B|=5.0T



Gaussian Weighted sum:
 $\mu = -0.01312$ cps
 $\sigma = 0.00958$ cps

#run	corrected counts within <u>roi</u>	error	B
24881	0.016430161	0.0173544826	5
24894	-0.0186506426	0.01484266	5
24907	-0.0565596898	0.0246868891	5
24920	0.00682909841	0.0175408731	5
24933	-0.0346497445	0.0163839068	5

Finding Probability/ neutron

Beam Intensity Measurements:

-Lowell Beam: 9.93×10^8 neutrons/s
-Au Foil: 7.4×10^8 neutrons/s

-Average Intensity: 8.7×10^8 neutrons/s
-Estimated Error: 1.3×10^8 neutrons/s
-Relative Error: 15%

$\mu = -0.01312$ n/s
Intensity = 8.7×10^8 n/s

$\mu/\text{intensity} = -1.5\text{E-}11$ probability per neutron
 $\sigma/(\text{intensity-estimated error}) = 1.3\text{E-}11$

Considering |B|=5.0T

Gaussian Weighted sum of corrected data:

$\mu = -0.01312$

$\sigma = 0.00958$

Gives:

Signal < 0.0026 [n/s] (95% Confidence Limit)

Signal < 0.0060 [n/s] (97.7% Confidence Limit)

Signal < 0.0092 [n/s] (99% Confidence Limit)

Comparing to established limits

From previous slide:

$\mu/\text{intensity} = -1.5\text{E-}11$ probability per neutron
 $\sigma/(\text{intensity-estimated error}) = 1.3\text{E-}11$

normaldist(-1.5,1.3)
Mean, Standard Deviation

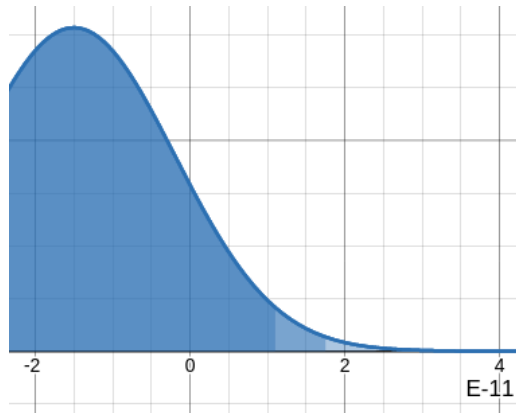
☒ Find Cumulative Probability (CDF)
Min: $-\infty$ Max: $\mu + 2\sigma$

normaldist(-1.5,1.3)
Mean, Standard Deviation

☒ Find Cumulative Probability (CDF)
Min: $-\infty$ Max: $\mu + 2.5\sigma$

normaldist(-1.5,1.3)
Mean, Standard Deviation

☒ Find Cumulative Probability (CDF)
Min: $-\infty$ Max: $\mu + 3\sigma$



Probability < 1.1 E-11 [1/n] (97.7% C.L.)
Probability < 1.75 E-11 [1/n] (99.4% C.L.)
Probability < 2.4 E-11 [1/n] (99.9% C.L.)

Found limit is $\sim 10^{-11}/n$, more accurate limit should be set with Feldman-Cousins approach

Thanks to Dr. Gonzalez for suggesting this format for C.L., also was recommended to use feldman-cousins statistics method or use poisson statistics to analyze data because of rarity of events

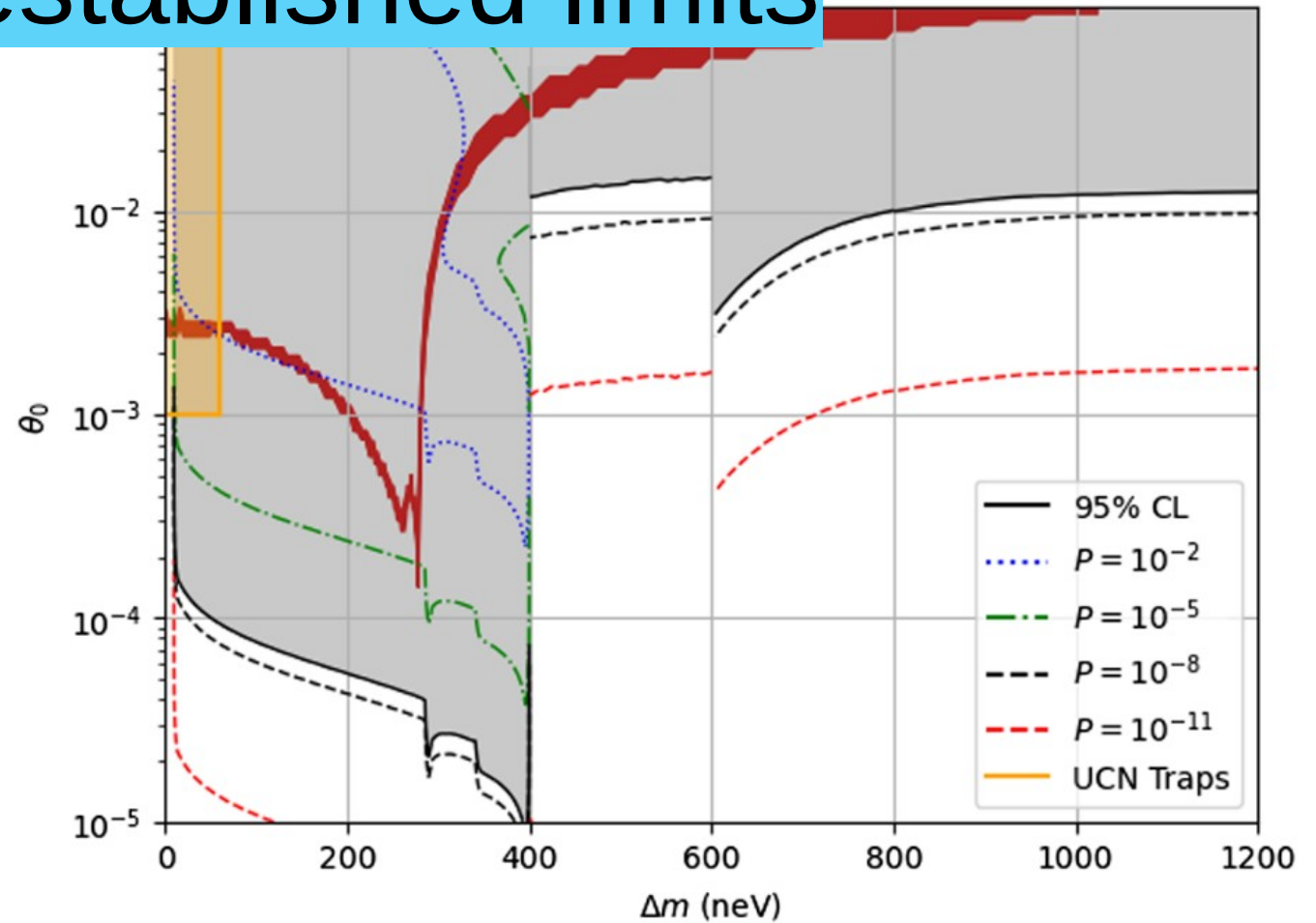


FIG. 3. The parameter space of the mirror matter model [19] excluded with 95% C.L. (gray region) and prediction consistent with the neutron lifetime anomaly (red band). Calculated probability of transmission is given by the dashed contour lines. The region 400–600 neV uses a different dataset.